

Online Representation Learning on the Open Web



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Computer Science Department, School of Computer Science
Carnegie Mellon University



Carnegie Mellon University

Computer Science Department

Committee

Deepak Pathak

Deva Ramanan

Alexei A. Efros

Consider this scenario:

Consider this scenario:



Task: classify bird species

Consider this scenario:



Task: classify bird species

Question: what do you do to get max performance?

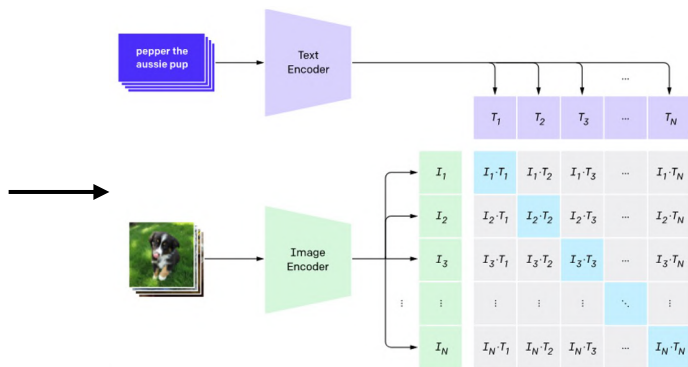
Current Paradigm: Transfer Learning

Current Paradigm: Transfer Learning



1. Some large dataset

Current Paradigm: Transfer Learning



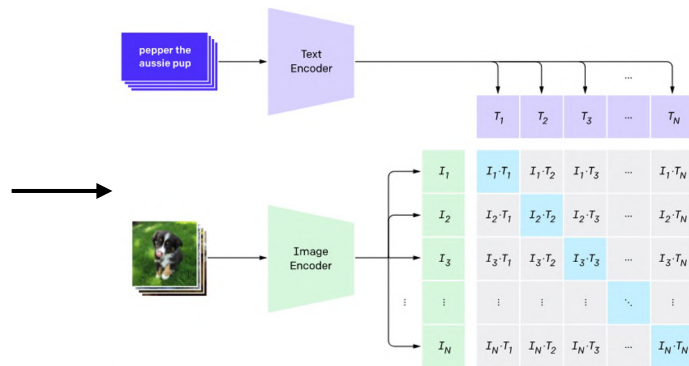
1. Some large dataset

2. Pretrained Model
(AlexNet, ResNet, CLIP)

Current Paradigm: Transfer Learning



1. Some large dataset

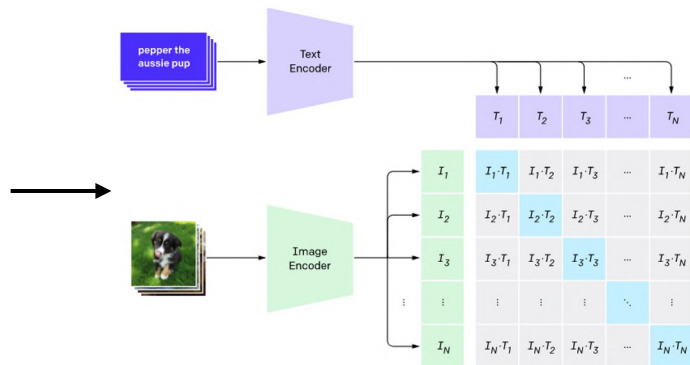


2. Pretrained Model
(AlexNet, ResNet, CLIP)



3. Fine-tune on target

Current Paradigm: Transfer Learning



1. Some large dataset

2. Pretrained Model
(AlexNet, ResNet, CLIP)

3. Fine-tune on target

Let's talk about this

Scale is getting bigger and bigger...

Scale is getting bigger and bigger...



1.2M

Scale is getting bigger and bigger...



1.2M



OpenAI
CLIP

400M

Scale is getting bigger and bigger...



1.2M



400M



5,000M





Static Datasets



Static Datasets

- Snapshot of the internet



 **OpenAI**
CLIP



Static Datasets

- Snapshot of the internet
- Instantly stale



Static Datasets

- Snapshot of the internet
- Instantly stale
- Curator's bias



 **OpenAI**
CLIP



Static Datasets

- Snapshot of the internet
- Instantly stale
- Curator's bias
- Worse for long-tail tasks



 **OpenAI**
CLIP



Static Datasets

- Snapshot of the internet
- Instantly stale
- Curator's bias
- Worse for long-tail tasks
- ...



 **OpenAI**
CLIP



Static Datasets



Internet: Billions of images uploaded **each day**



 **OpenAI**
CLIP



Static Datasets



Internet: Billions of images uploaded **each day**

Static datasets are miniscule and out-of-date in comparison to the Internet!

Internet Explorer

Targeted Representation Learning on the Open Web

Alexander C. Li*, Ellis Brown*, Alexei A. Efros, Deepak Pathak



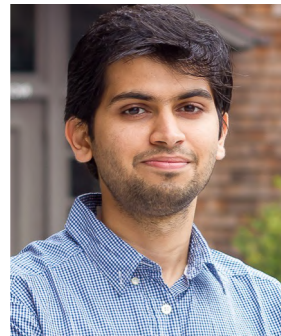
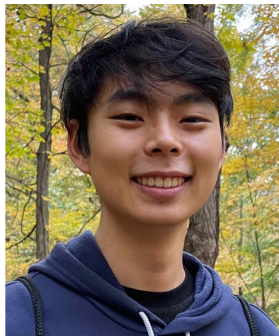
Accepted at ICML 2023



Internet Explorer

Targeted Representation Learning on the Open Web

Alexander C. Li*, Ellis Brown*, Alexei A. Efros, Deepak Pathak



Our proposal

Our proposal

Treat *Internet* itself as a dataset

Our proposal

Treat *Internet* itself as a dataset

open-ended

Our proposal

Treat *Internet* itself as a dataset

open-ended

constantly growing

Our proposal

Treat *Internet* itself as a dataset

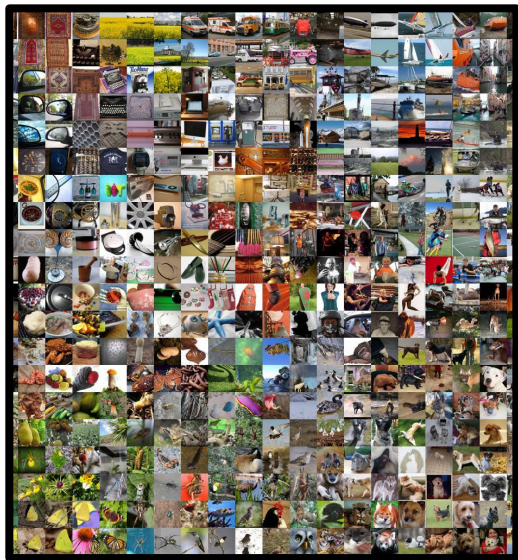
open-ended

constantly growing

always up-to-date

Current paradigm

Current paradigm

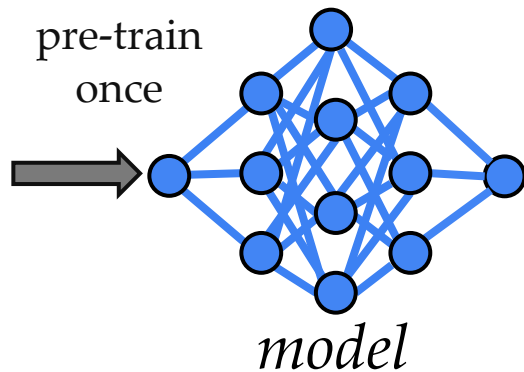


static dataset

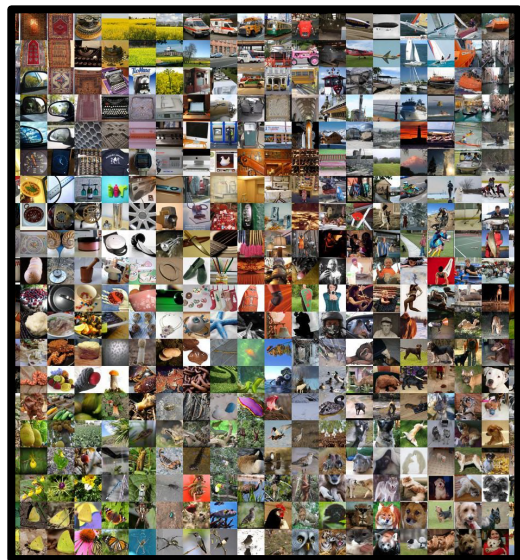
Current paradigm



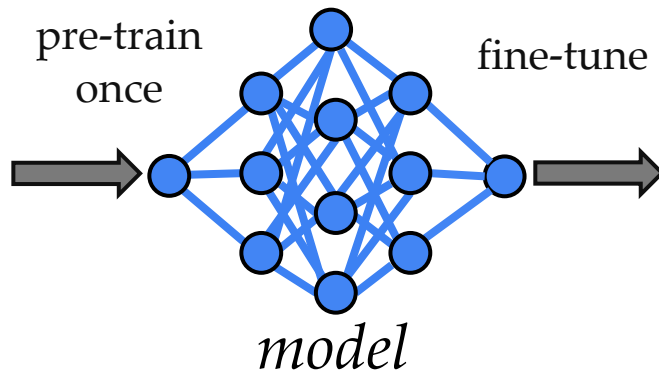
static dataset



Current paradigm



static dataset



target dataset

Our setting

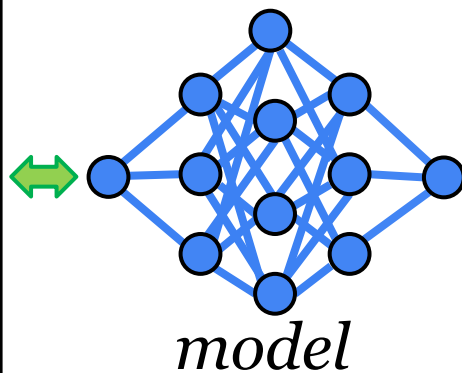


target dataset

Our setting



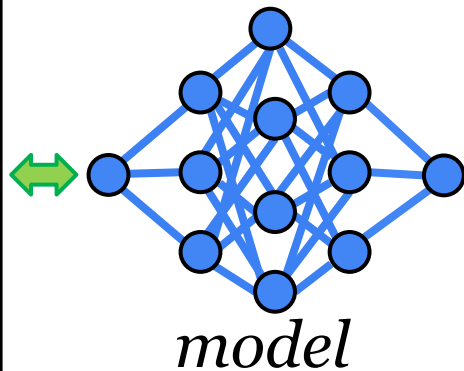
target dataset



Our setting



target dataset

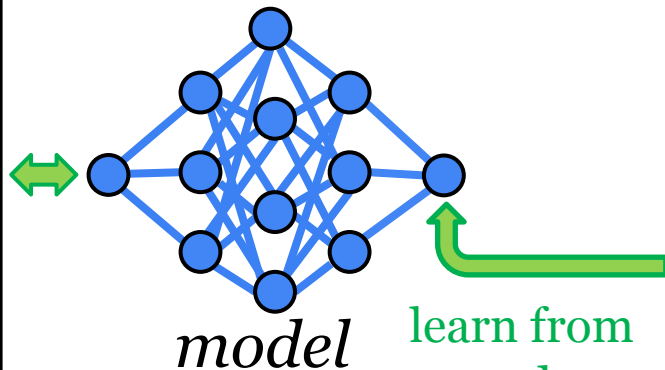


Internet

Our setting



target dataset



learn from
new data

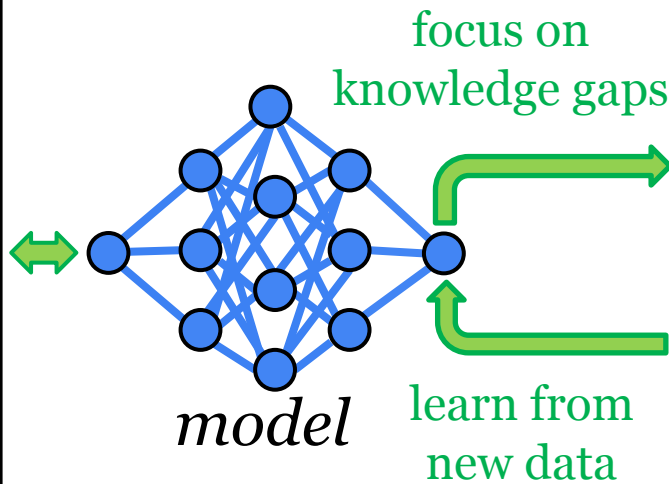


Internet

Our setting



target dataset

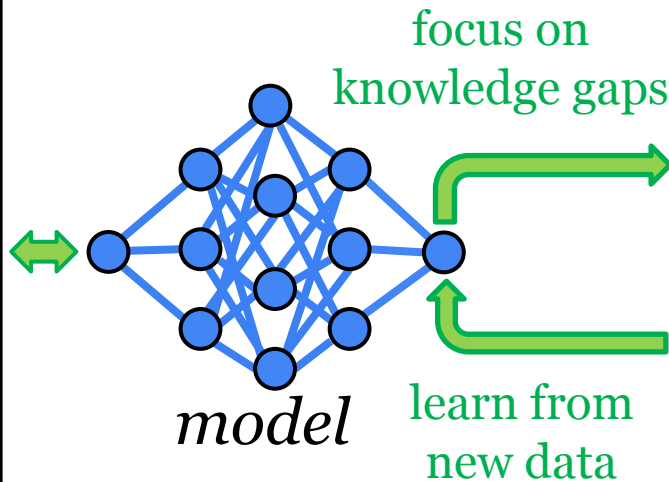


Internet

Our setting



target dataset



Internet

“Internet Explorer”

What can we do with the full breadth of the Internet?

What can we do with the full breadth of the Internet?



Learn features for any task

What can we do with the full breadth of the Internet?



Learn features for any task



Cover long-tail corner cases

What can we do with the full breadth of the Internet?



Learn features for any task



Cover long-tail corner cases



Find up-to-date data

Challenges

.

.

.

.

Challenges

- What to search for?

Challenges

- What to search for?
- How to search for it?

Challenges

- What to search for?
- How to search for it?
- What data is good?

Challenges

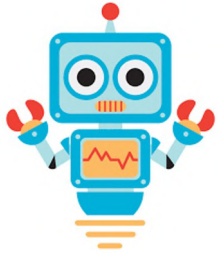
- What to search for?
- How to search for it?
- What data is good?
- How to integrate the data into our model?

Analogy to Reinforcement Learning

Analogy to Reinforcement Learning

Robot Explorer

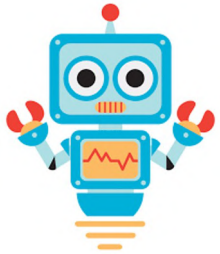
Analogy to Reinforcement Learning



Agent

Robot Explorer

Analogy to Reinforcement Learning



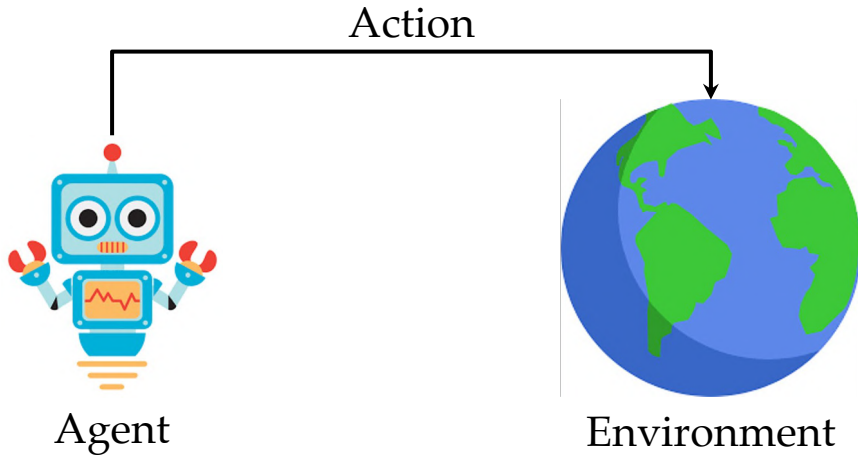
Agent



Environment

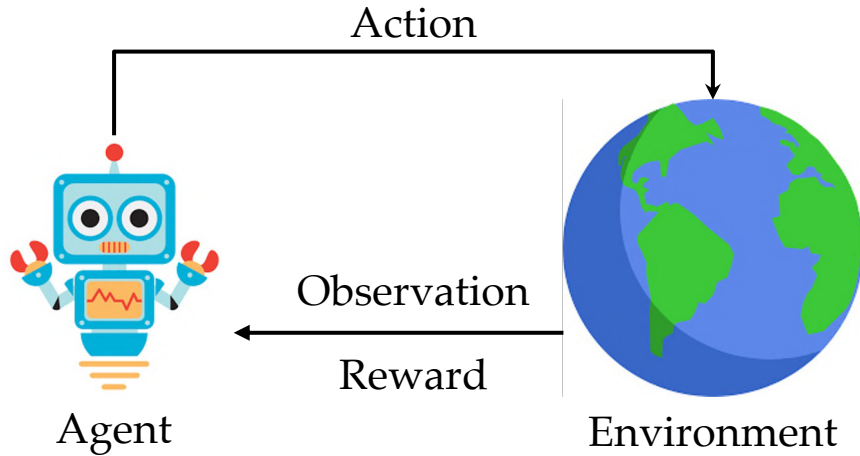
Robot Explorer

Analogy to Reinforcement Learning



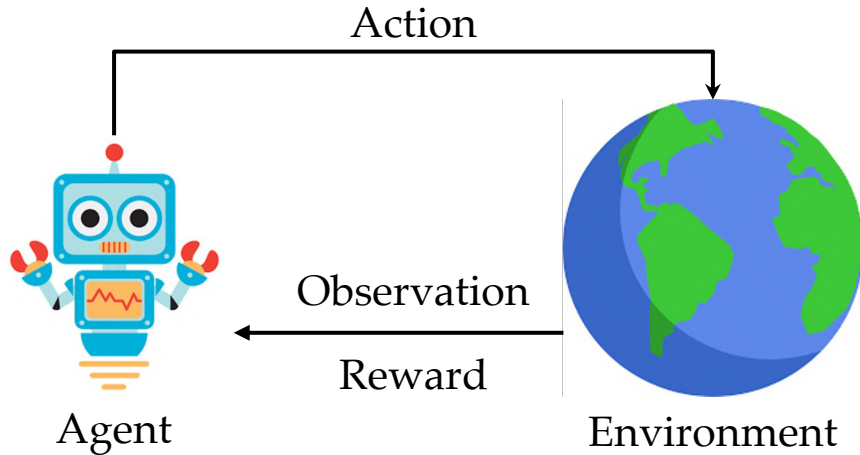
Robot Explorer

Analogy to Reinforcement Learning



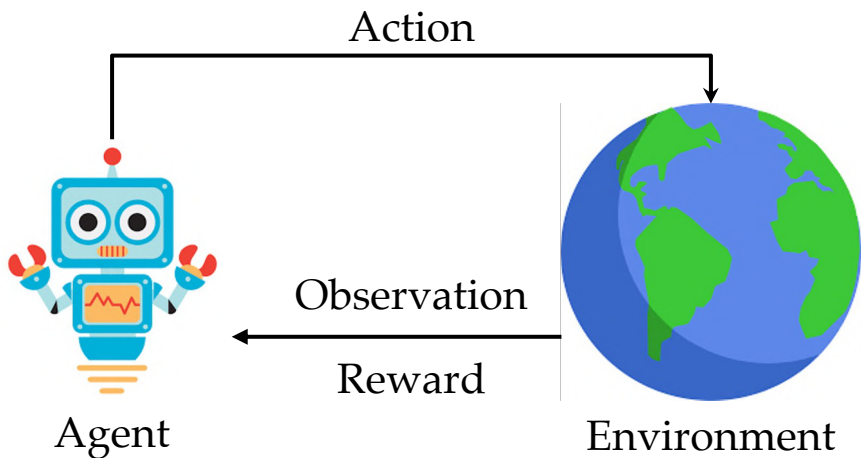
Robot Explorer

Analogy to Reinforcement Learning



Robot Explorer

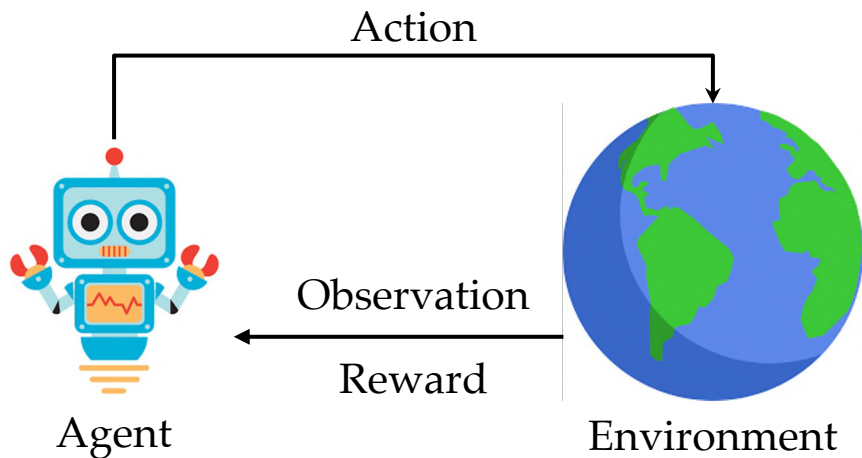
Analogy to Reinforcement Learning



Robot Explorer

Internet Explorer

Analogy to Reinforcement Learning

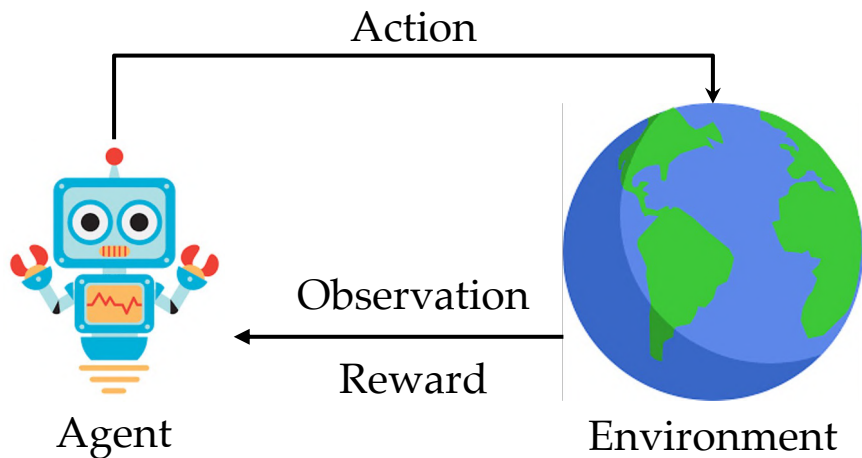


Robot Explorer

Environment → Internet

Internet Explorer

Analogy to Reinforcement Learning



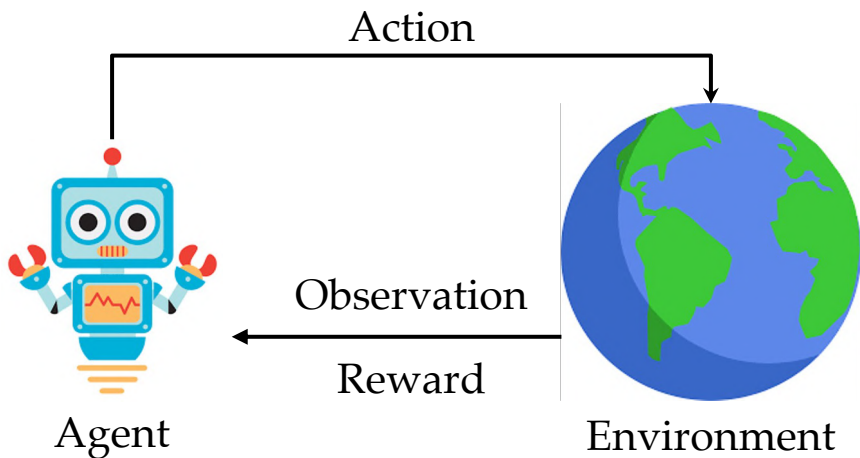
Robot Explorer

Environment \rightarrow Internet

Action \rightarrow search engine queries

Internet Explorer

Analogy to Reinforcement Learning



Robot Explorer

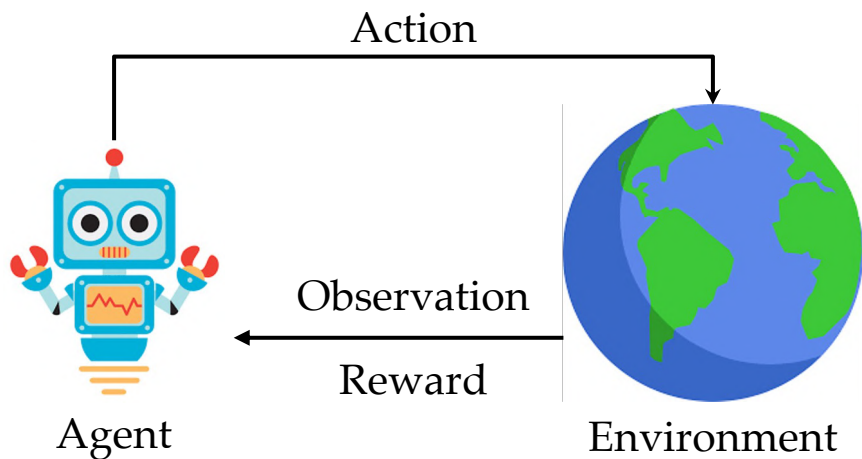
Environment → Internet

Action → search engine queries

Observation → Internet results

Internet Explorer

Analogy to Reinforcement Learning



Robot Explorer

Environment → Internet

Action → search engine queries

Observation → Internet results

Reward → relevant training data

Internet Explorer

Internet Explorer Method

Internet Explorer Method

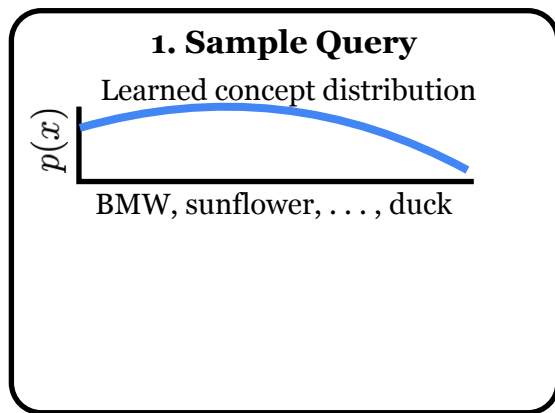
1. Sample Query

Internet Explorer Method

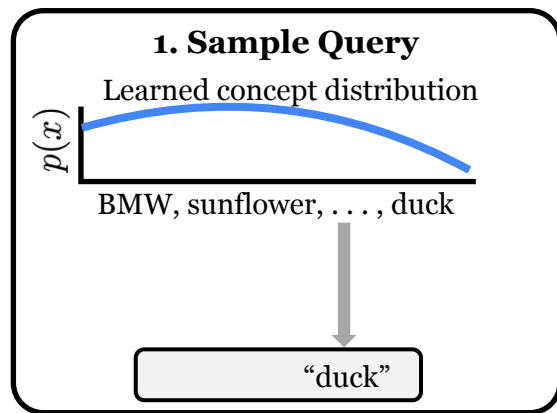
1. Sample Query

BMW, sunflower, . . . , duck

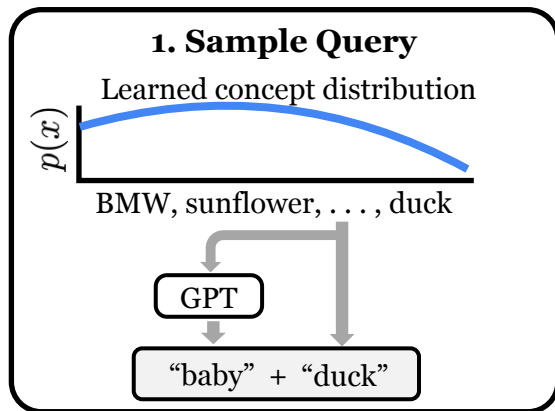
Internet Explorer Method



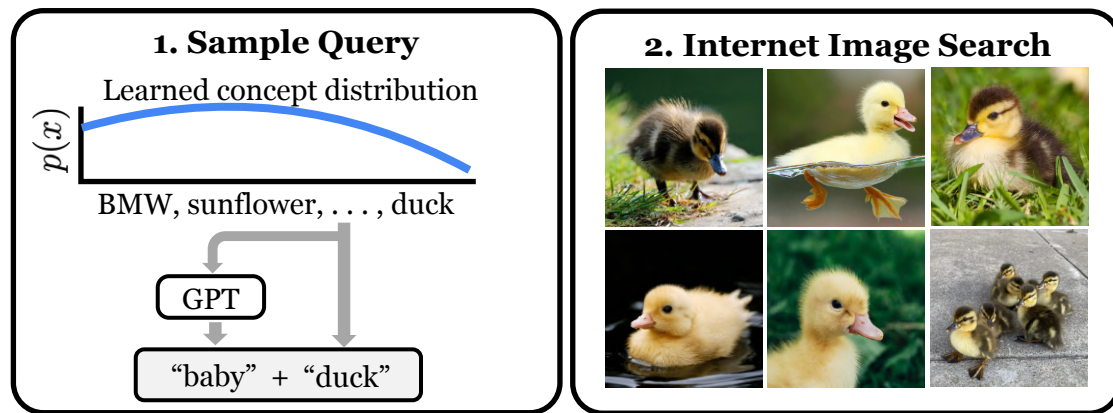
Internet Explorer Method



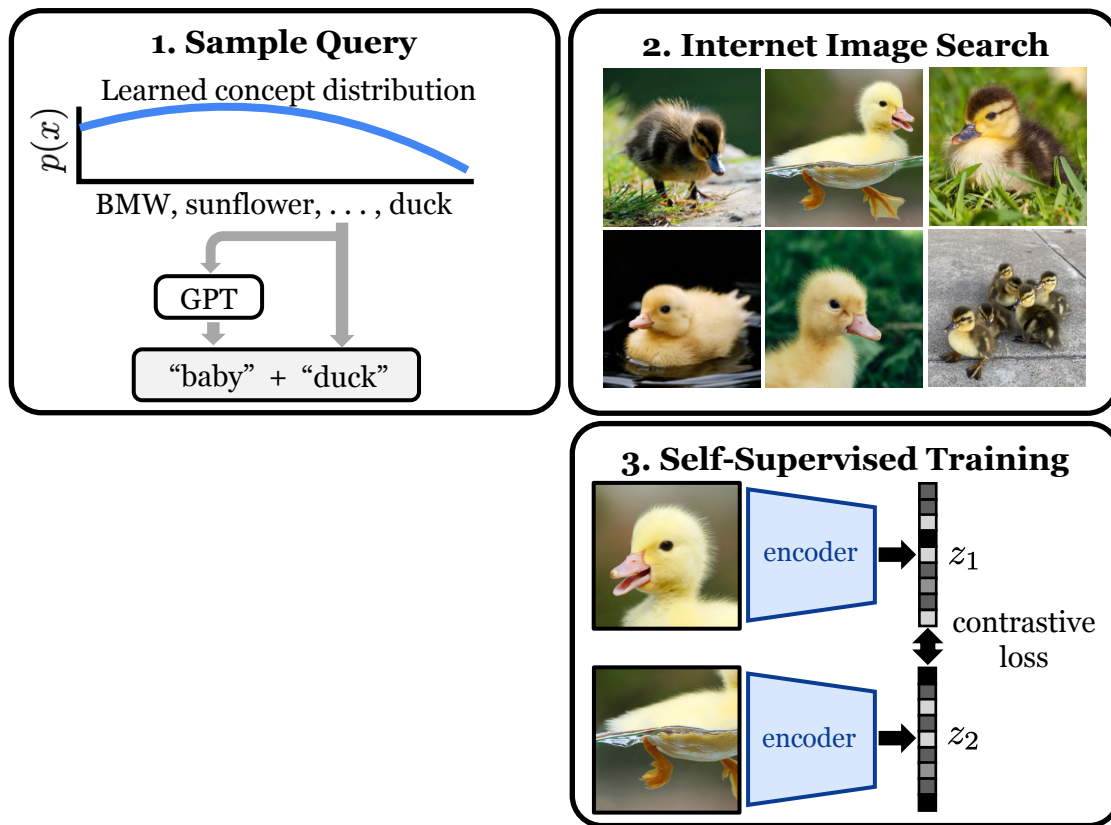
Internet Explorer Method



Internet Explorer Method

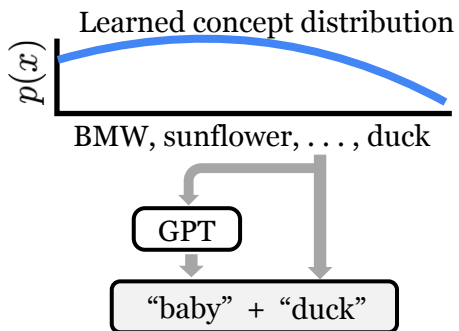


Internet Explorer Method



Internet Explorer Method

1. Sample Query

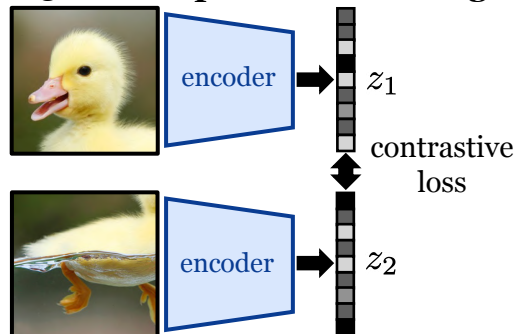


2. Internet Image Search



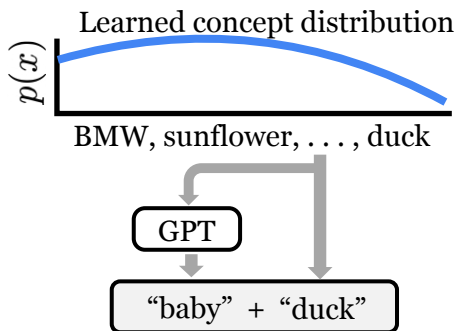
4. Update Concept Distribution

3. Self-Supervised Training



Internet Explorer Method

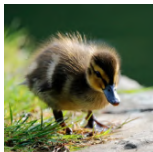
1. Sample Query



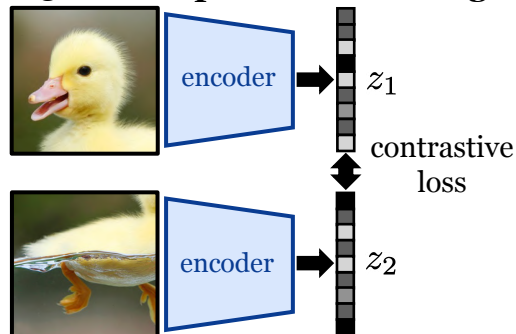
2. Internet Image Search



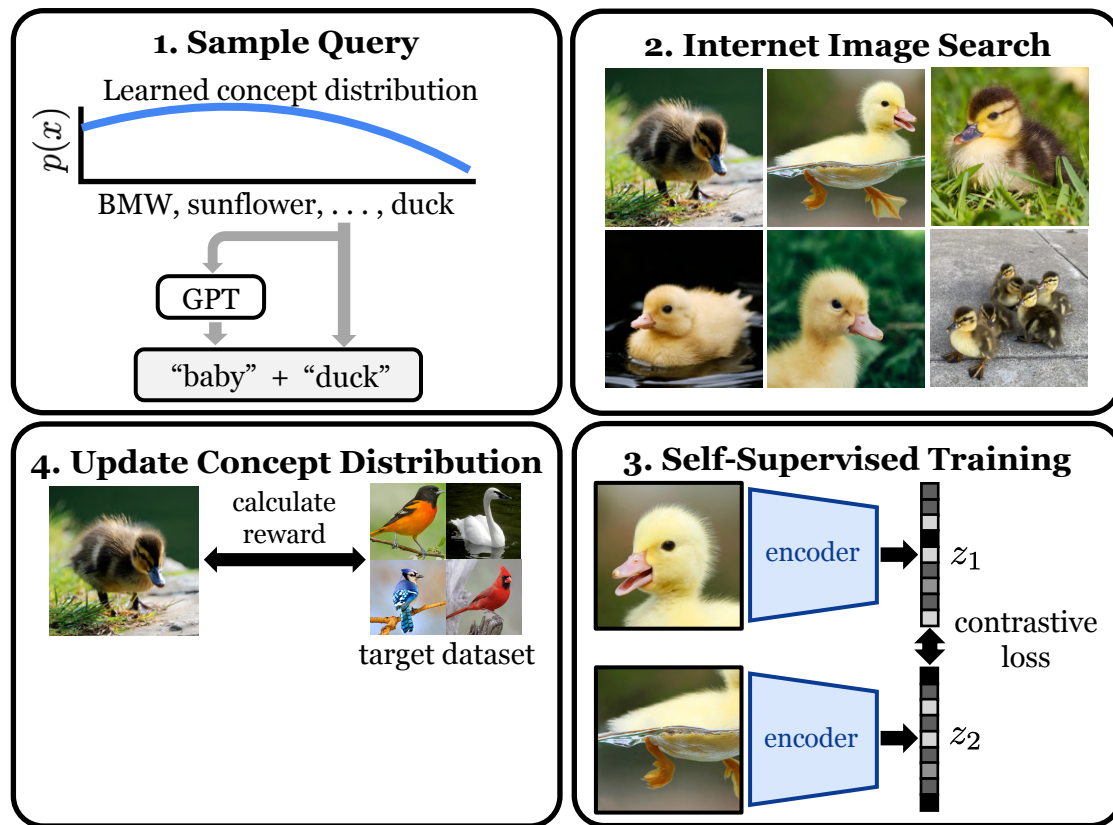
4. Update Concept Distribution



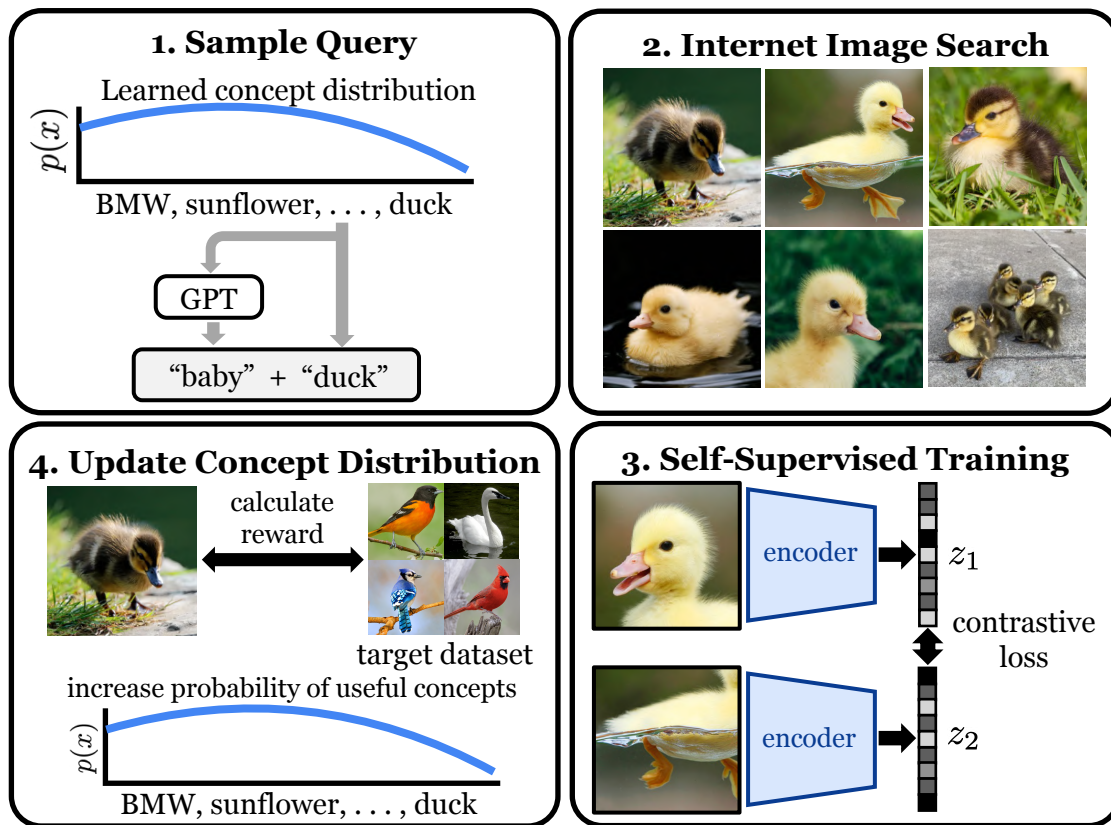
3. Self-Supervised Training



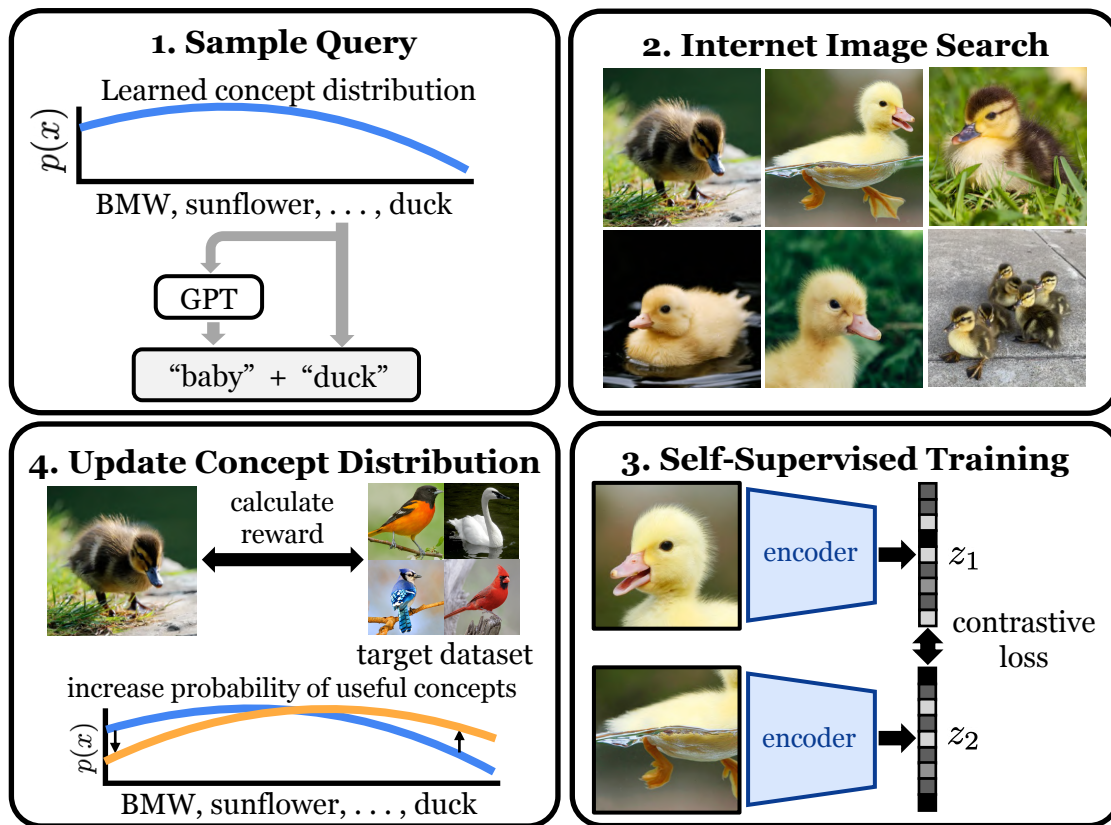
Internet Explorer Method



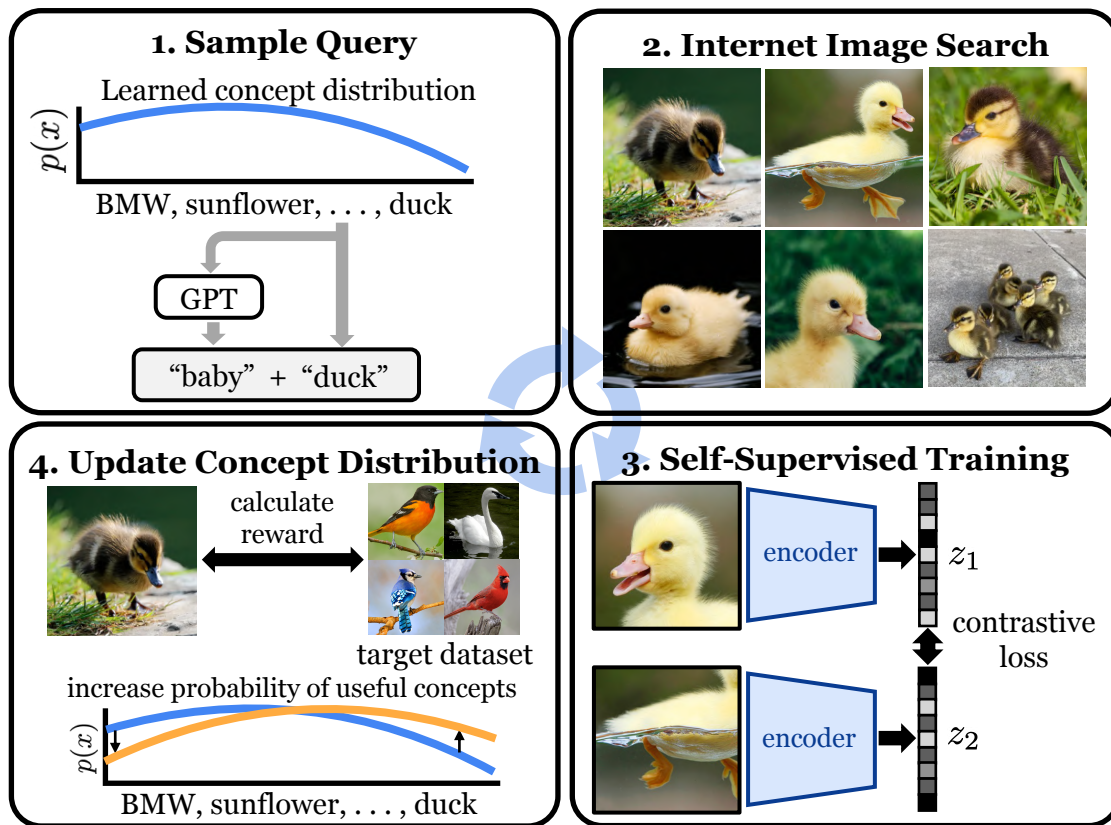
Internet Explorer Method



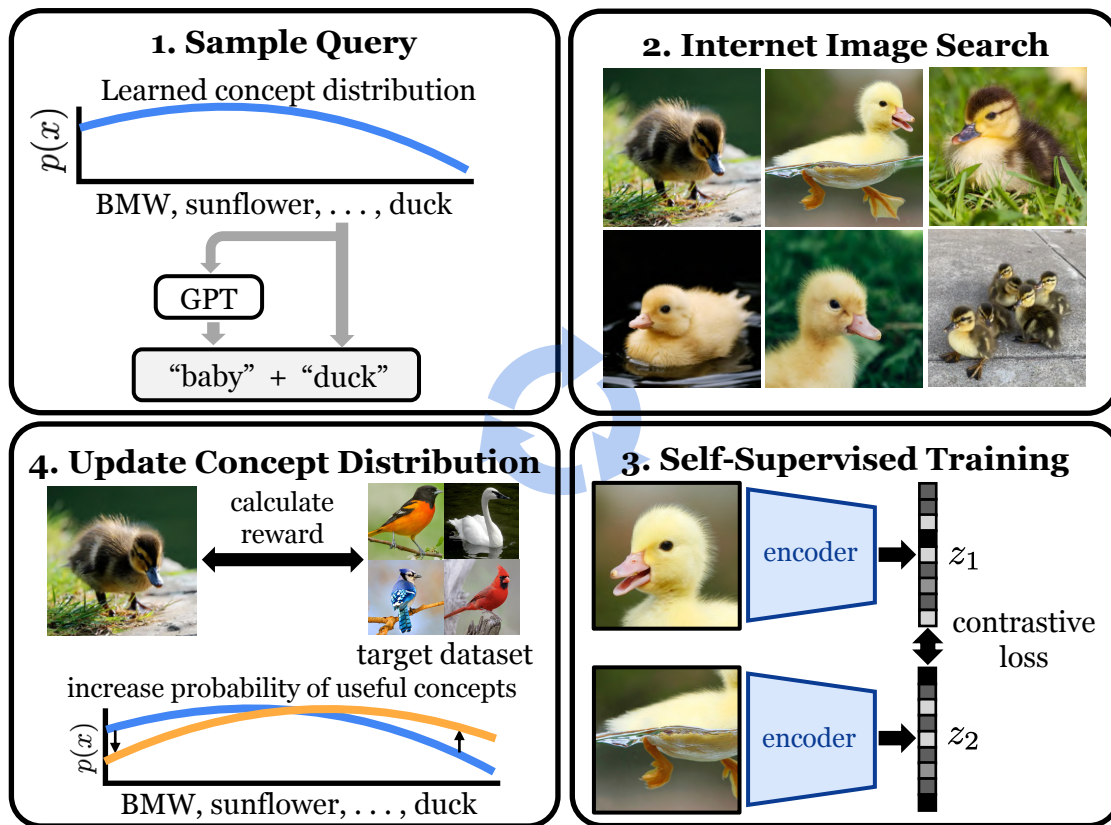
Internet Explorer Method



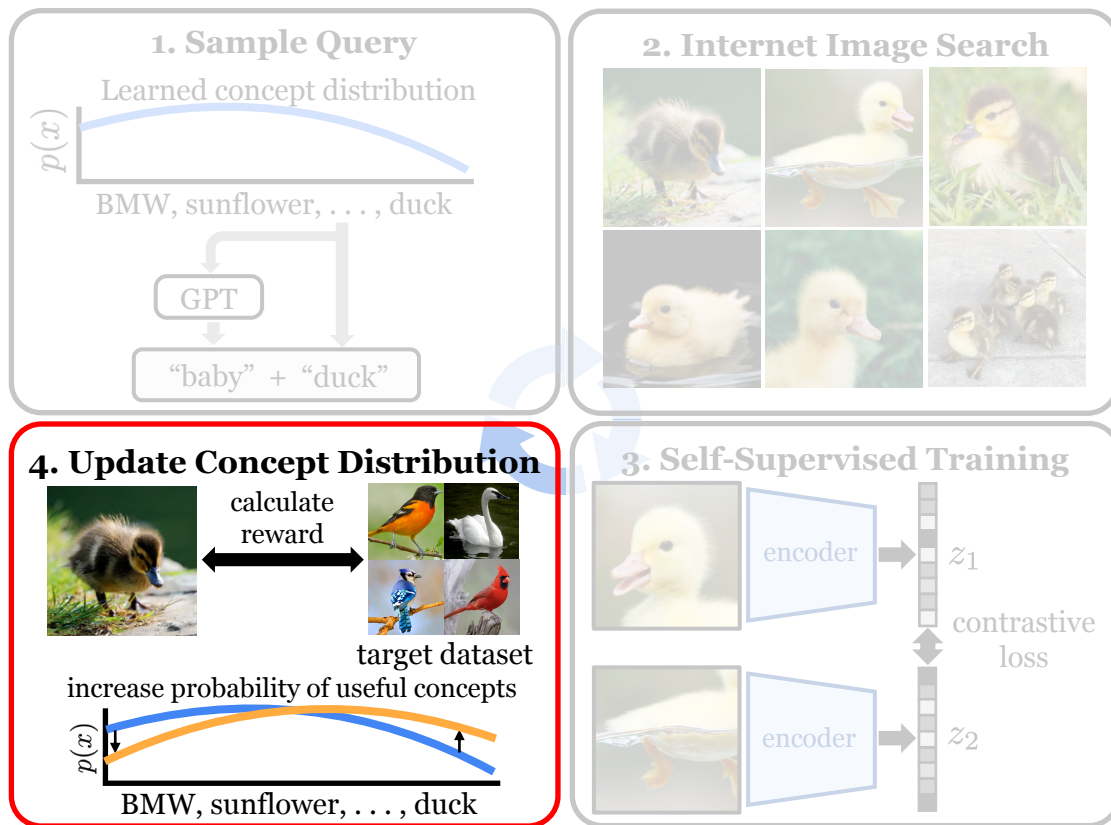
Internet Explorer Method



Internet Explorer Method

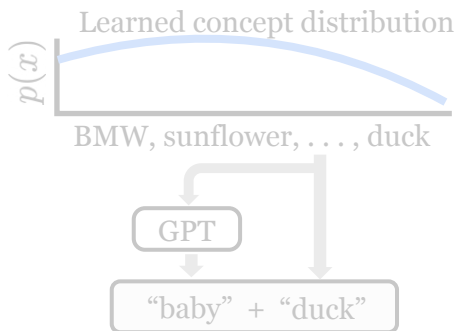


Internet Explorer Method



Internet Explorer Method

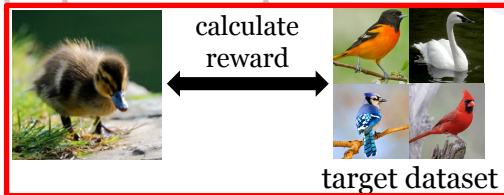
1. Sample Query



2. Internet Image Search



4. Update Concept Distribution



increase probability of useful concepts



3. Self-Supervised Training

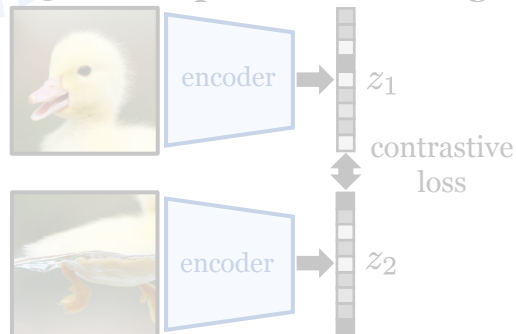


Image Reward (prioritize relevant *images*)

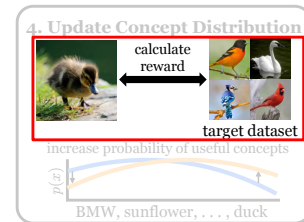
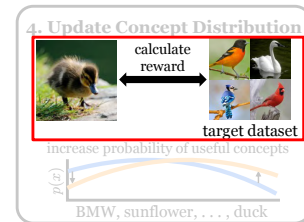
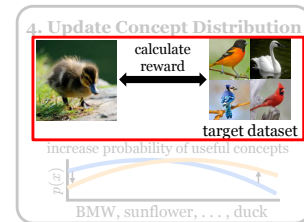


Image Reward (prioritize relevant *images*)



“steam buns”
downloaded
image #1

Image Reward (prioritize relevant *images*)

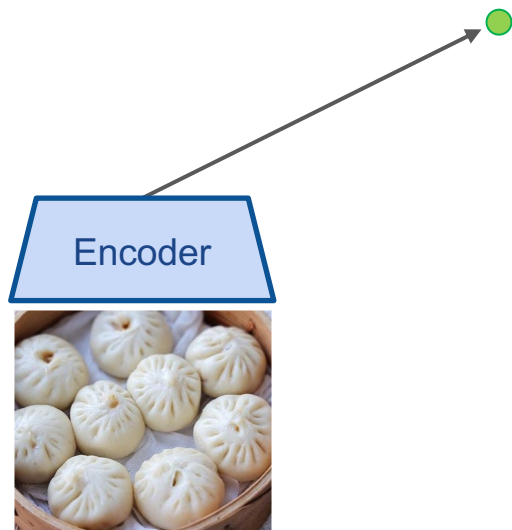


Encoder



“steam buns”
downloaded
image #1

Image Reward (prioritize relevant *images*)



“steam buns”
downloaded
image #1

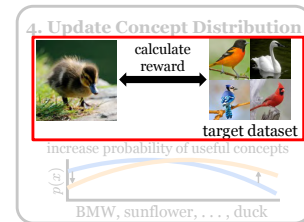
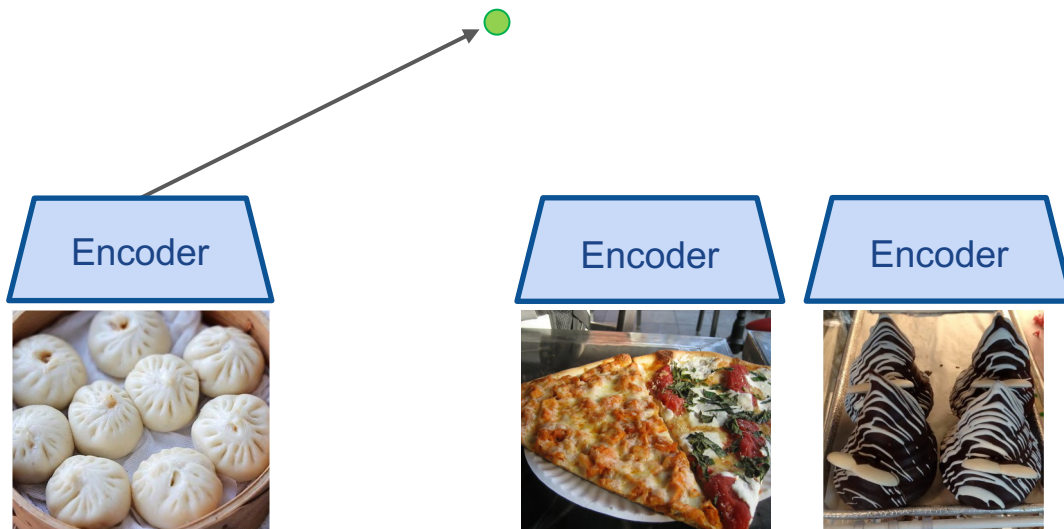
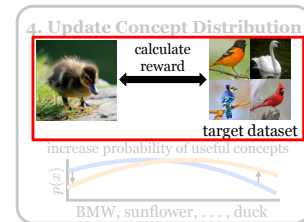


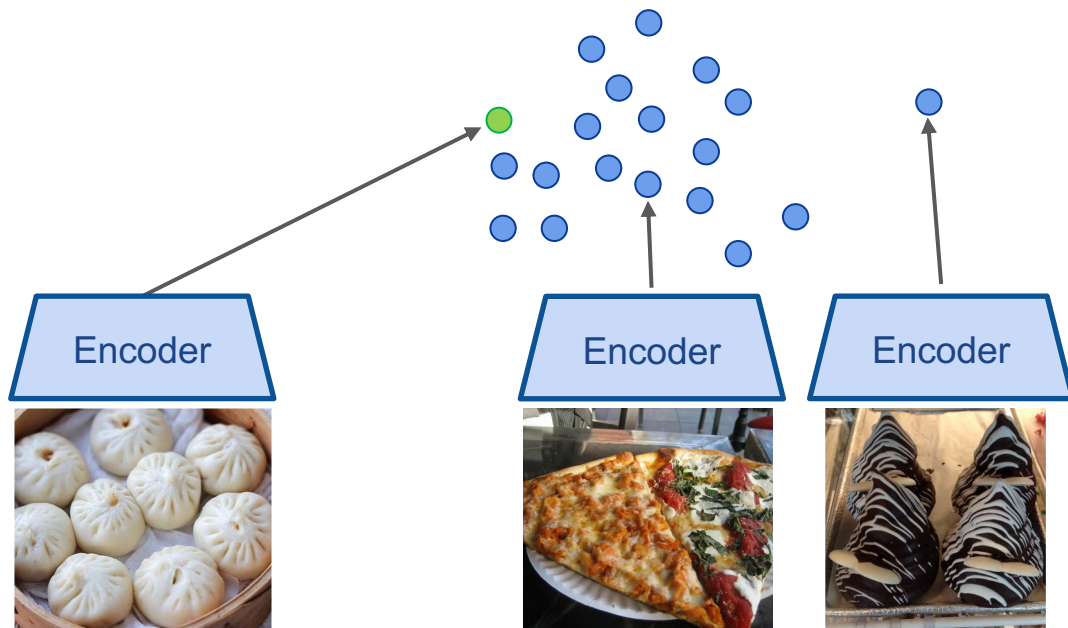
Image Reward (prioritize relevant *images*)



“steam buns”
downloaded
image #1

Food101
Target dataset images

Image Reward (prioritize relevant *images*)



“steam buns”
downloaded
image #1

Food101
Target dataset images

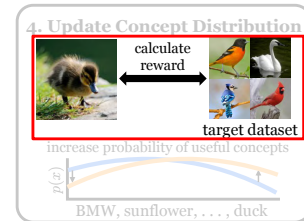
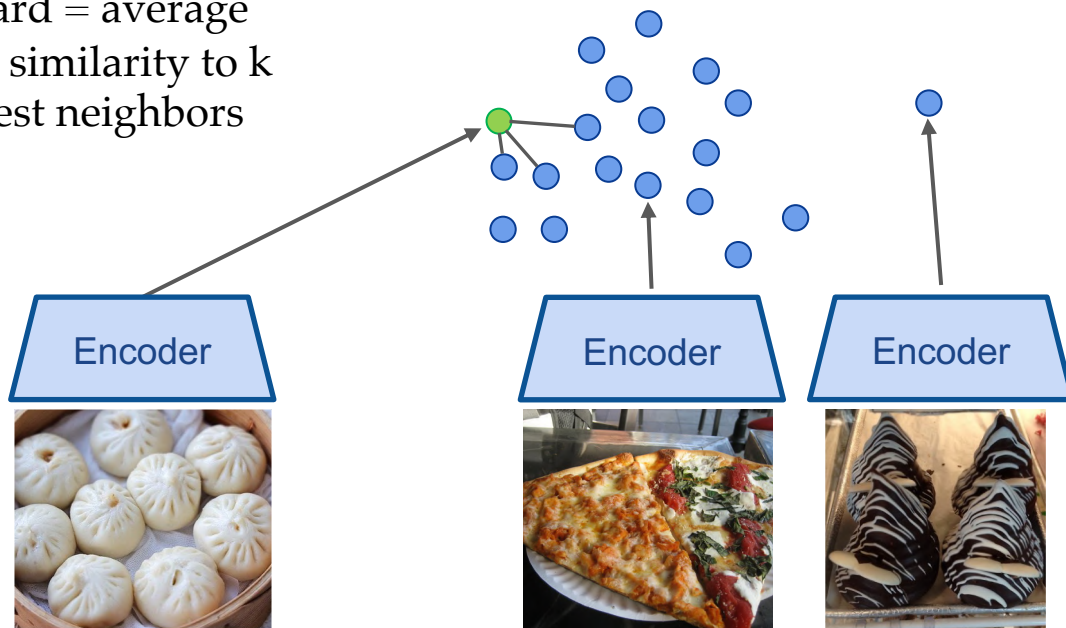


Image Reward (prioritize relevant *images*)

Reward = average cosine similarity to k nearest neighbors



“steam buns”
downloaded
image #1

Food101
Target dataset images

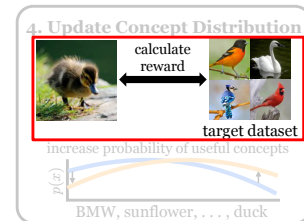


Image Reward (prioritize relevant *images*)

Reward = average cosine similarity to k nearest neighbors

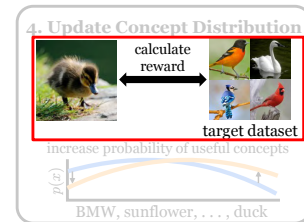
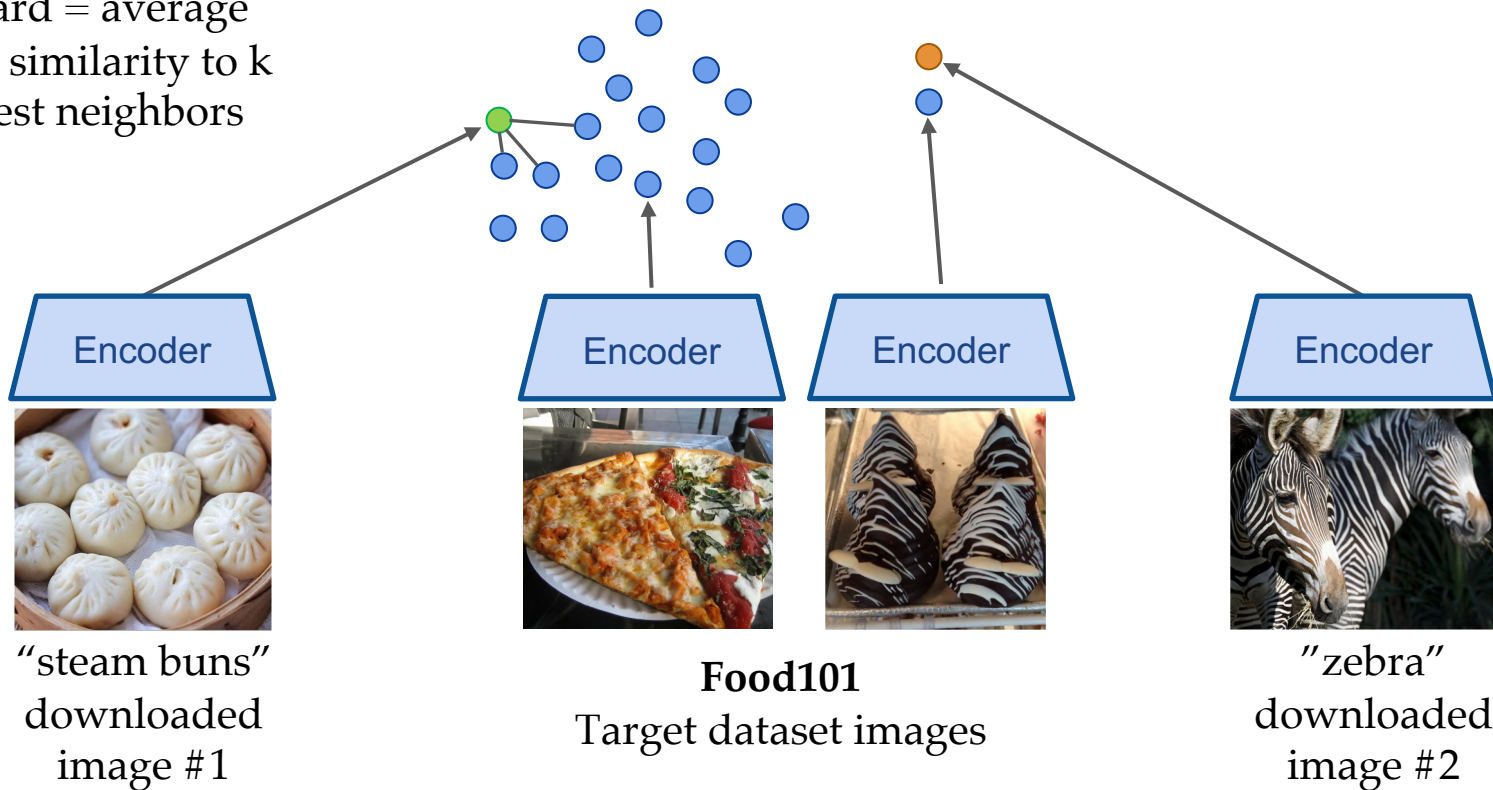
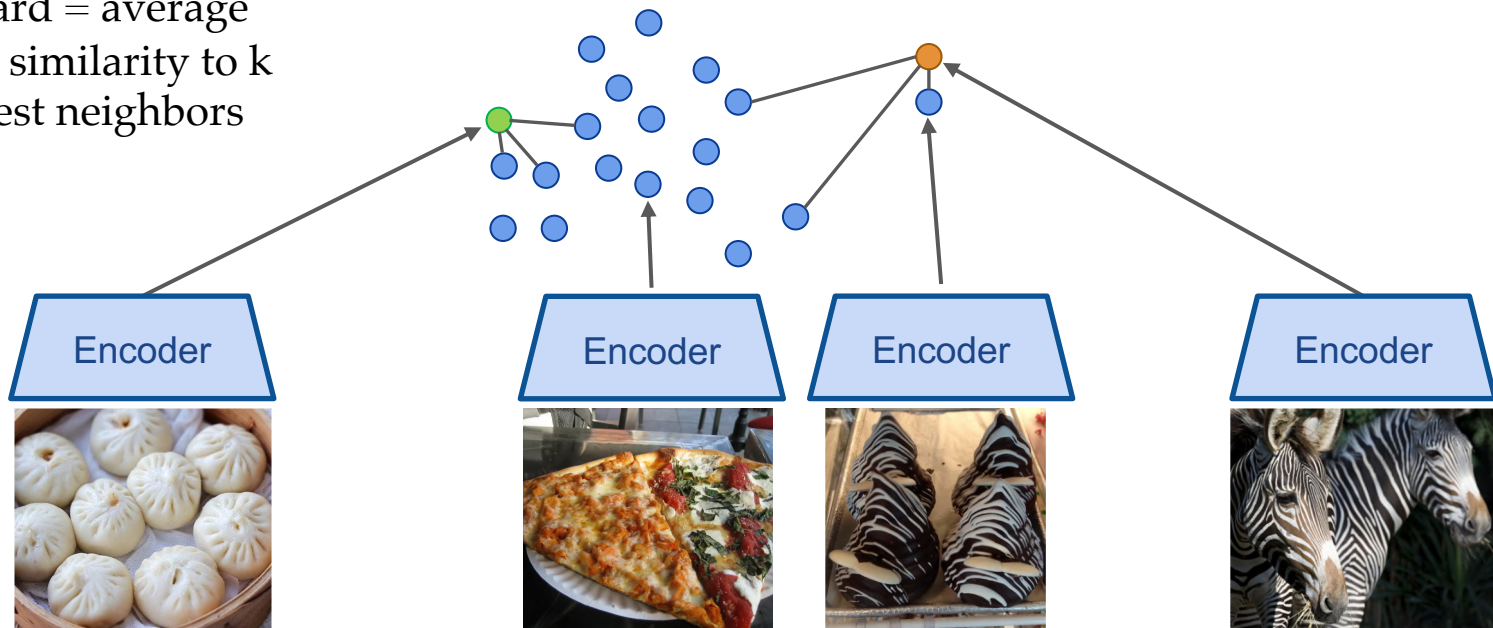


Image Reward (prioritize relevant *images*)

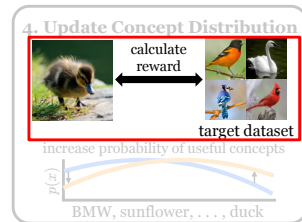
Reward = average cosine similarity to k nearest neighbors



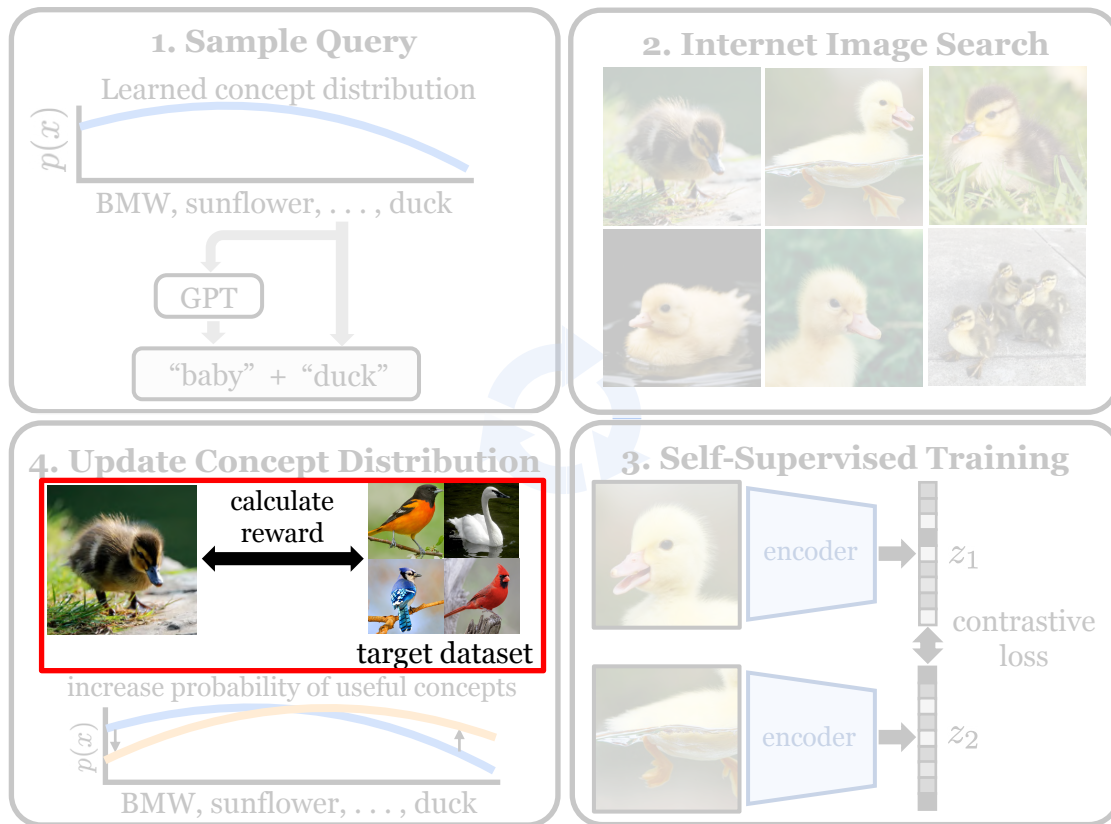
"steam buns"
downloaded
image #1

Food101
Target dataset images

"zebra"
downloaded
image #2



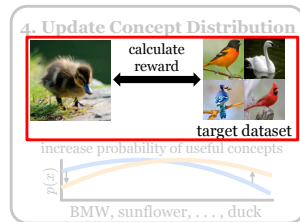
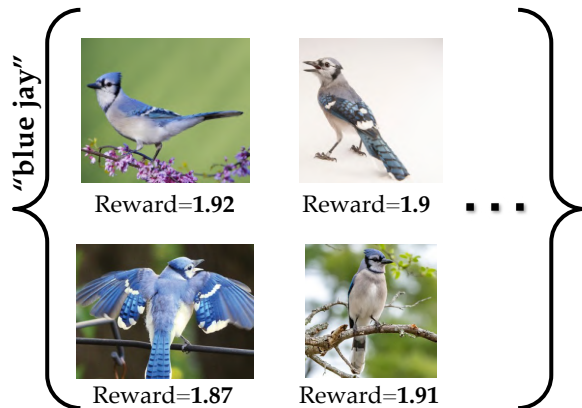
Internet Explorer Method



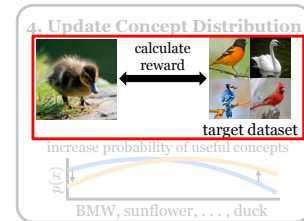
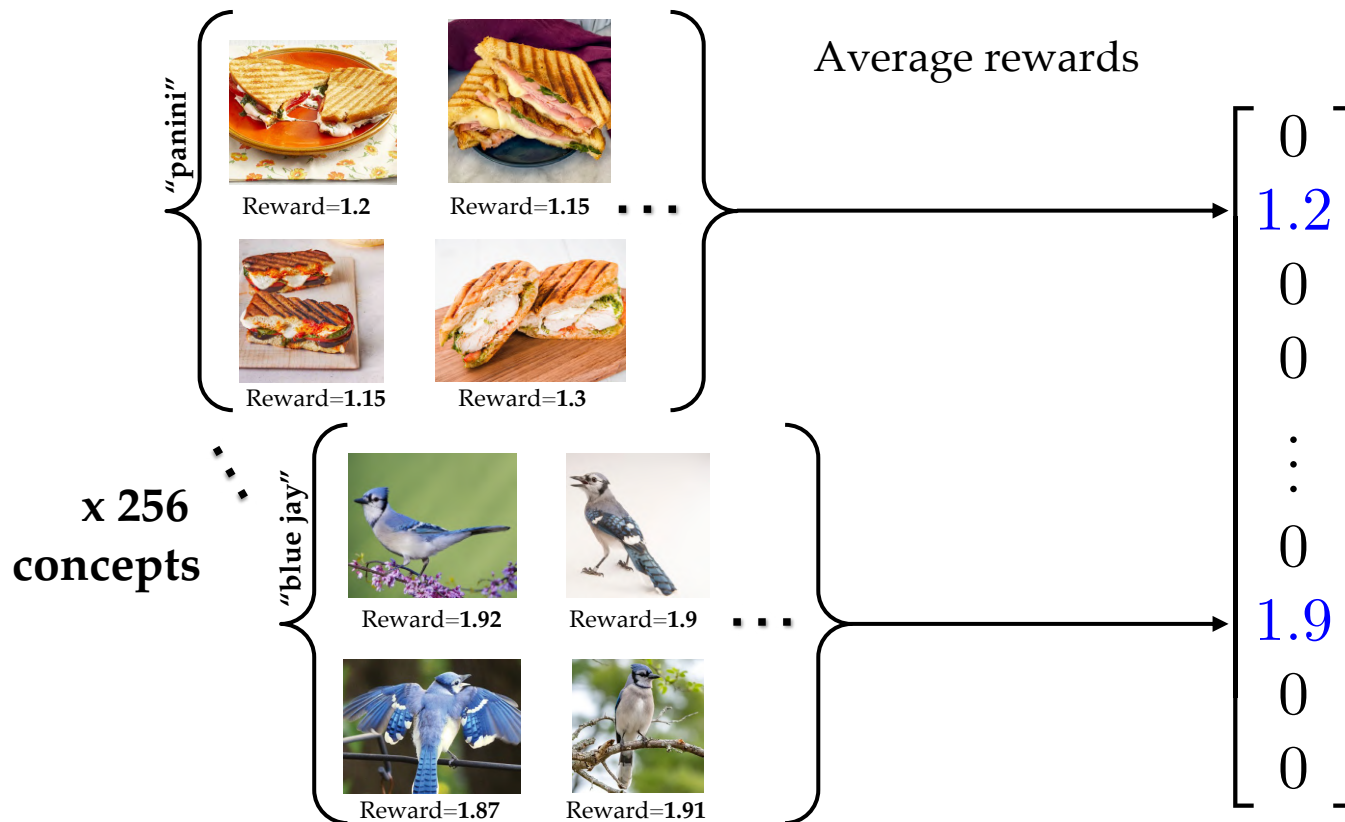
Concept Reward (prioritize relevant *concepts*)



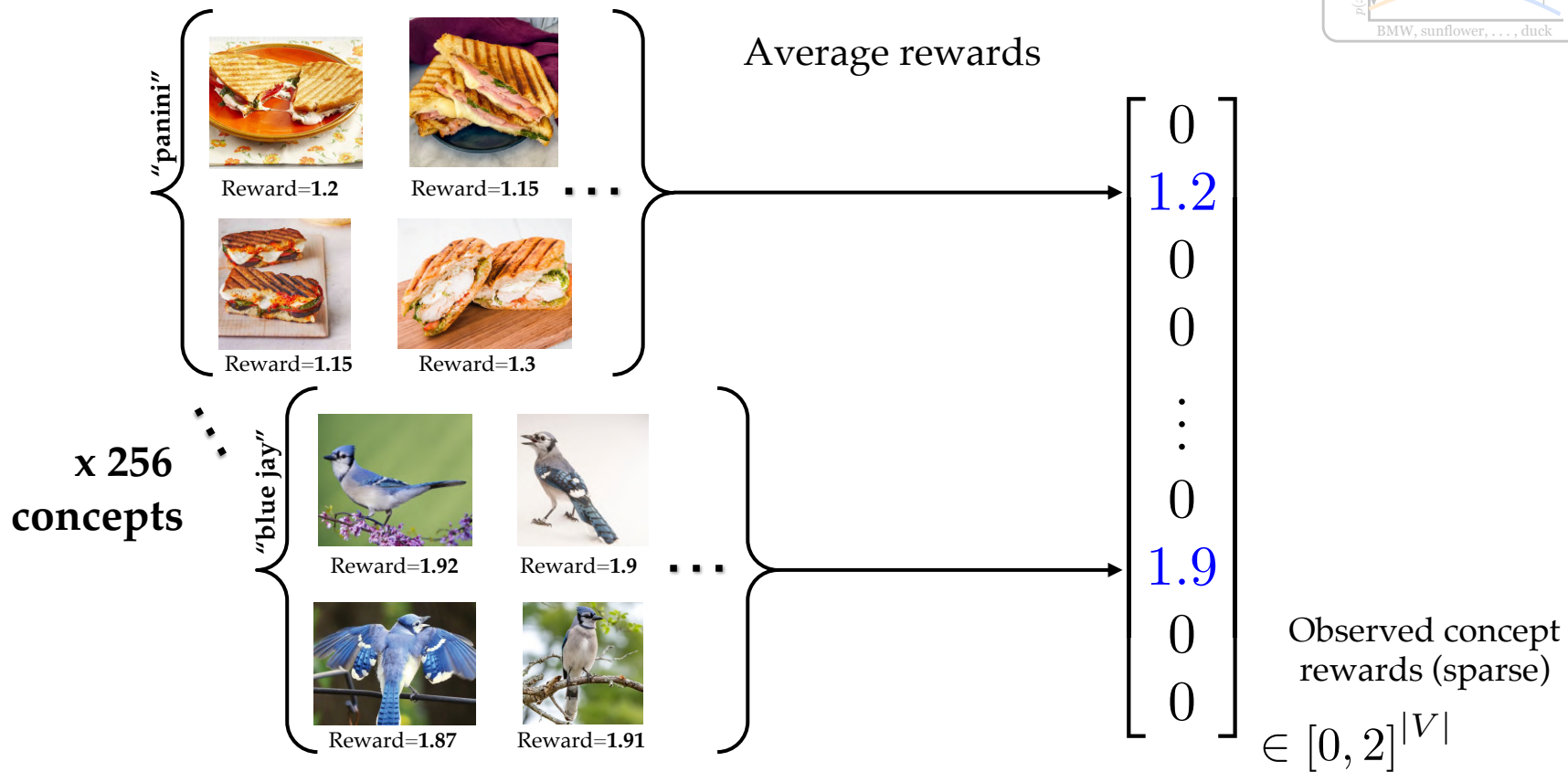
x 256
concepts



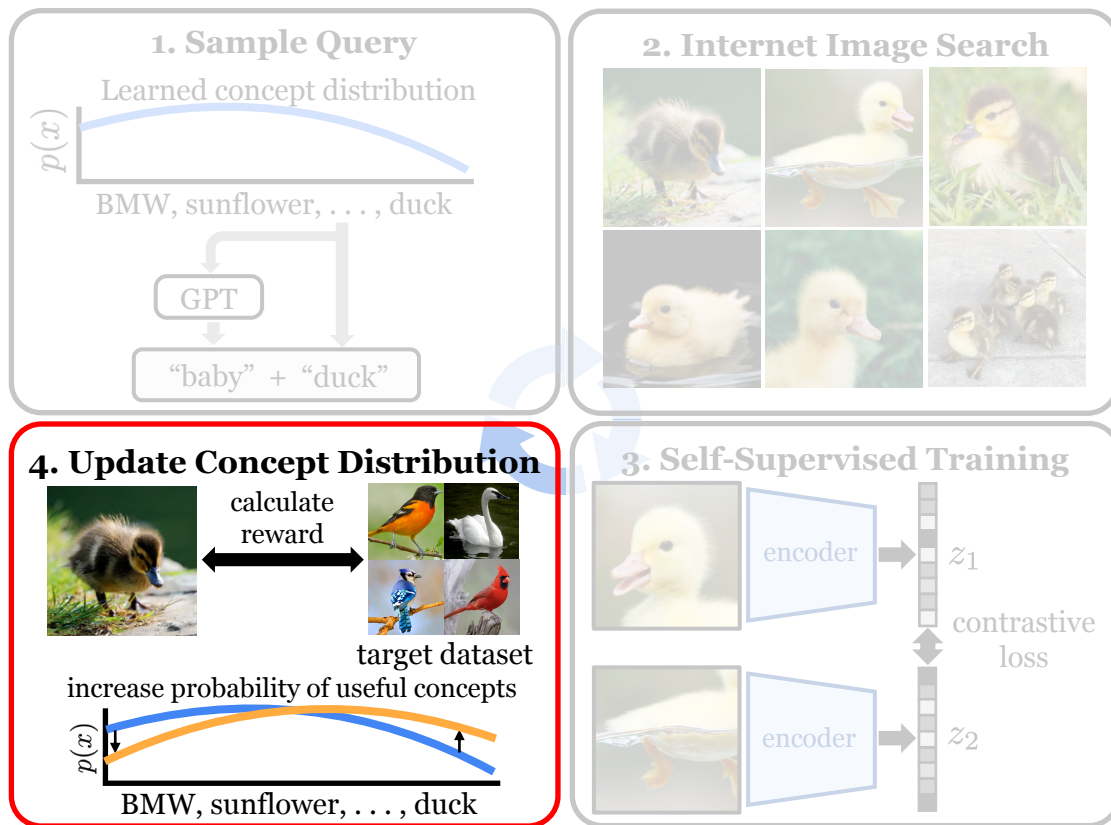
Concept Reward (prioritize relevant *concepts*)



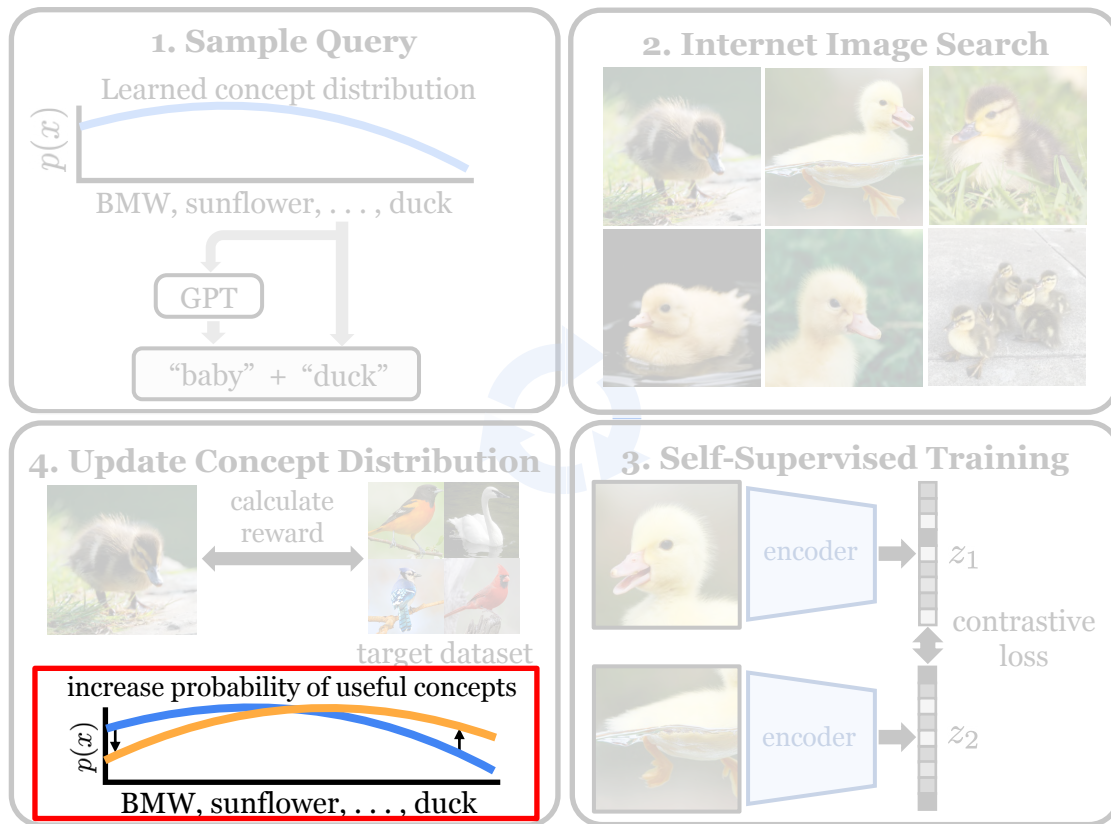
Concept Reward (prioritize relevant *concepts*)



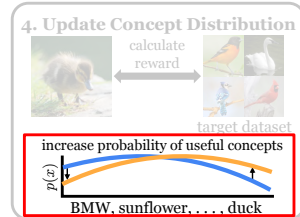
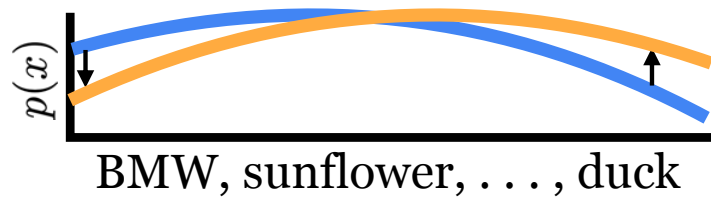
Internet Explorer Method



Internet Explorer Method

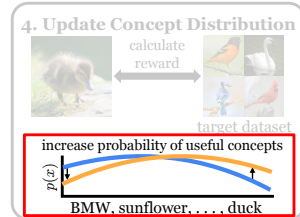
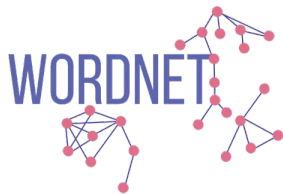
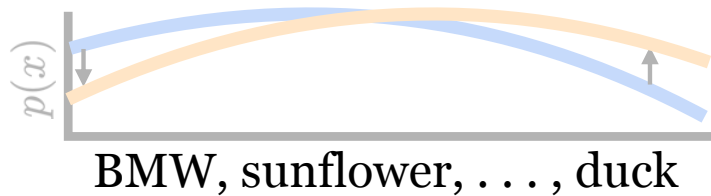


Concept Distribution



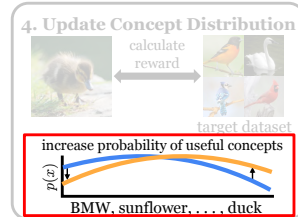
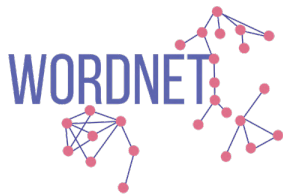
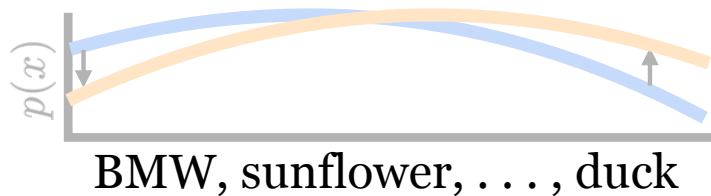
Concept Distribution

- Vocabulary size: $|V| \approx 150\text{k}$ concepts



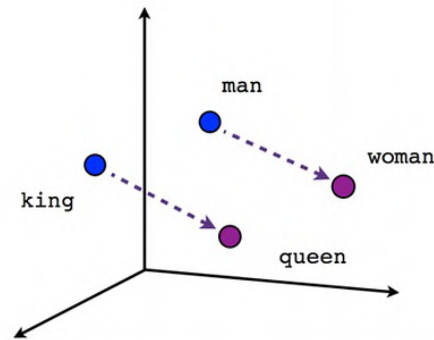
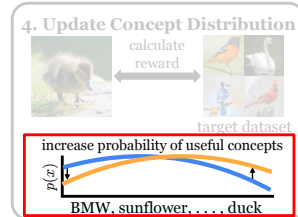
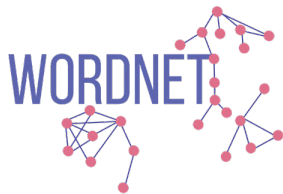
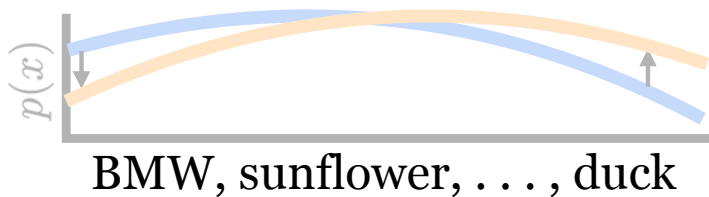
Concept Distribution

- Vocabulary size: $|V| \approx 150\text{k}$ concepts
- Want to estimate value of unseen concepts from just a few thousand results



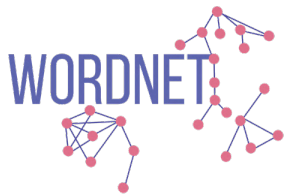
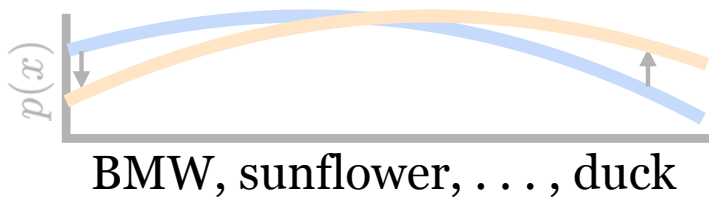
Concept Distribution

- Vocabulary size: $|V| \approx 150\text{k}$ concepts
- Want to estimate value of unseen concepts from just a few thousand results

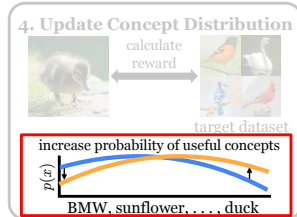
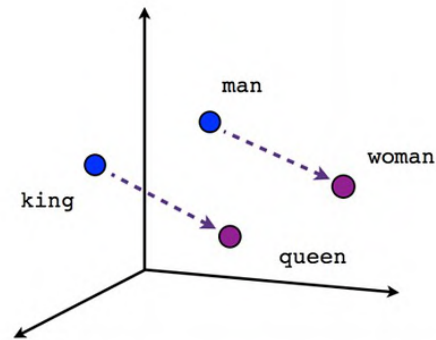


Concept Distribution

- Vocabulary size: $|V| \approx 150\text{k}$ concepts
- Want to estimate value of unseen concepts from just a few thousand results

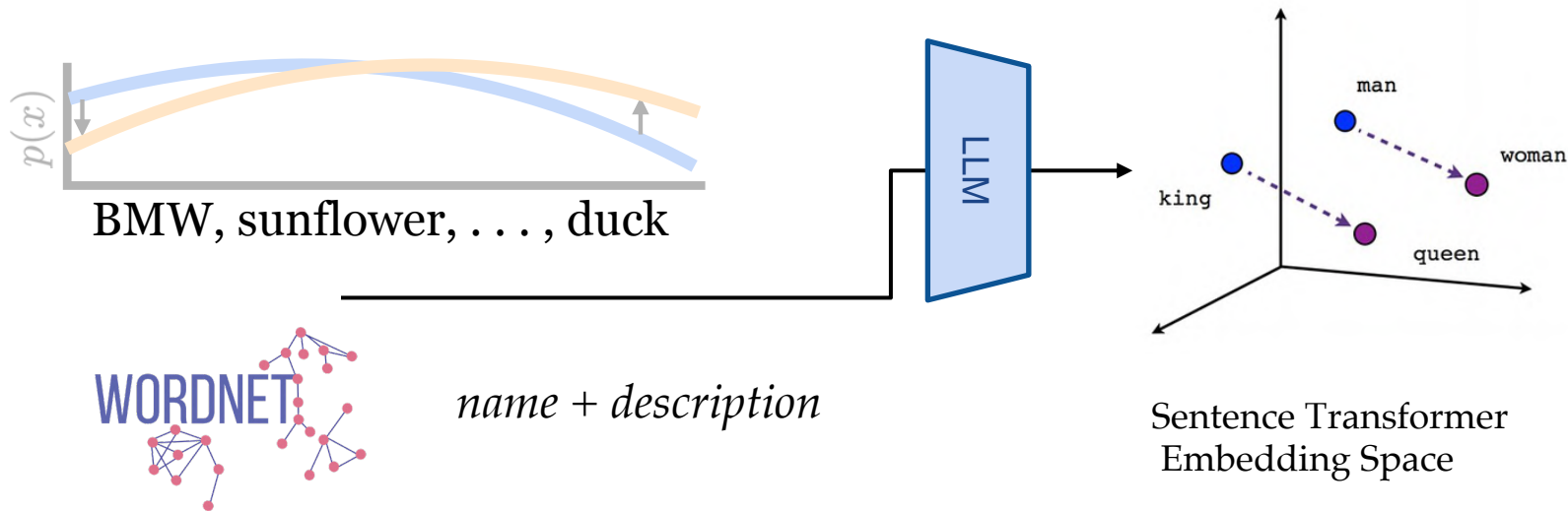
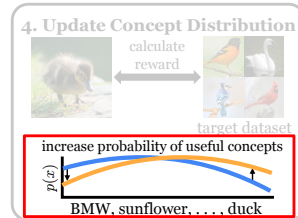


name + description

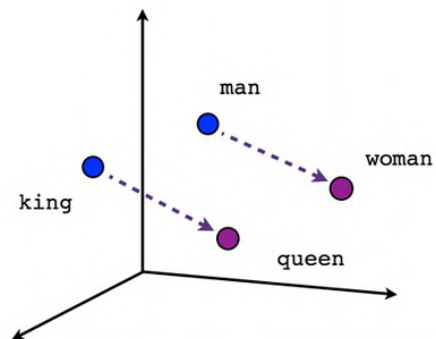
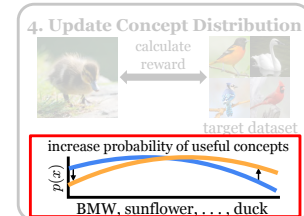


Concept Distribution

- Vocabulary size: $|V| \approx 150\text{k}$ concepts
- Want to estimate value of unseen concepts from just a few thousand results

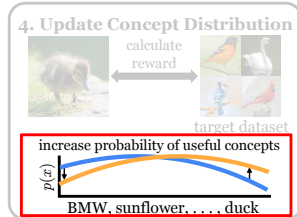


“Prospecting” in concept-embedding space

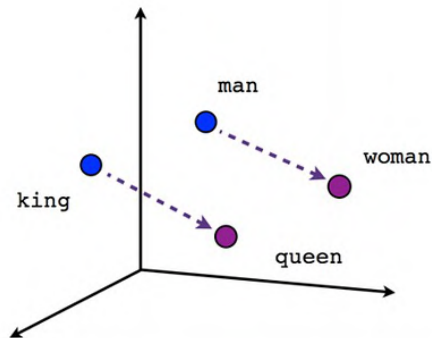


Sentence Transformer
Embedding Space

“Prospecting” in concept-embedding space

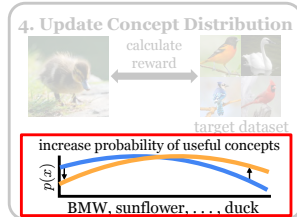

$$\begin{bmatrix} 0 \\ 1.2 \\ 0 \\ 0 \\ \vdots \\ 0 \\ 1.9 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

Observed concept
rewards (sparse)

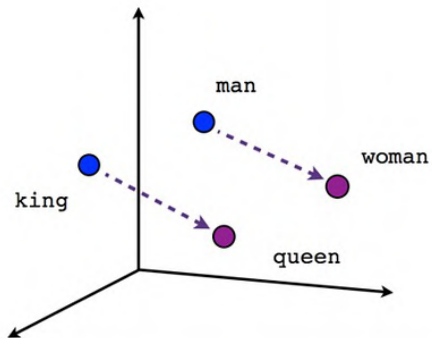


Sentence Transformer
Embedding Space

“Prospecting” in concept-embedding space


$$\begin{bmatrix} 0 \\ 1.2 \\ 0 \\ 0 \\ \vdots \\ 0 \\ 1.9 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

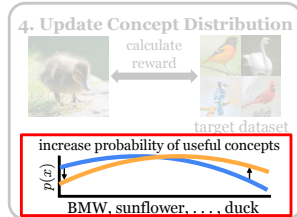
Observed concept
rewards (sparse)



Sentence Transformer
Embedding Space

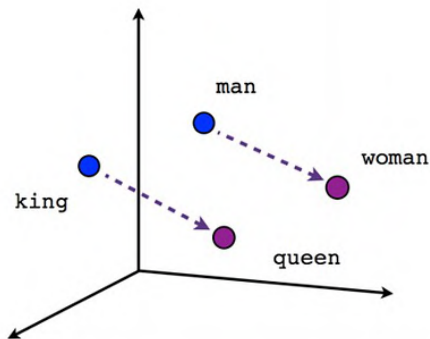


“Prospecting” in concept-embedding space

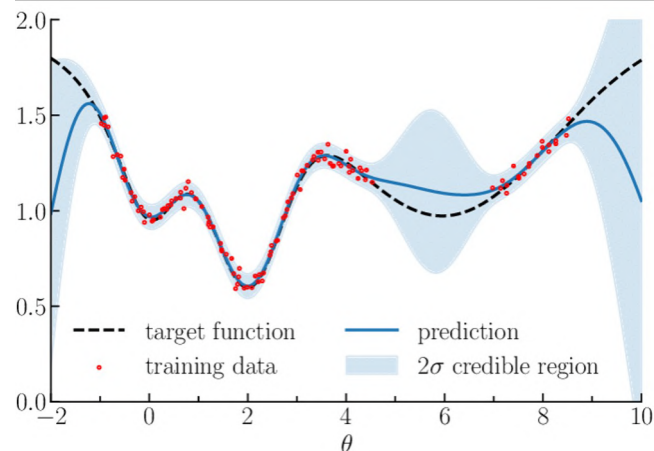


$\begin{bmatrix} 0 \\ 1.2 \\ 0 \\ 0 \\ \vdots \\ 0 \\ 1.9 \\ 0 \\ 0 \end{bmatrix}$

Observed concept rewards (sparse)

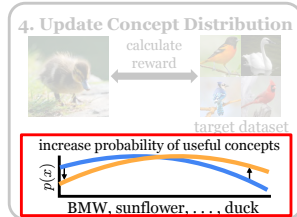


Sentence Transformer Embedding Space



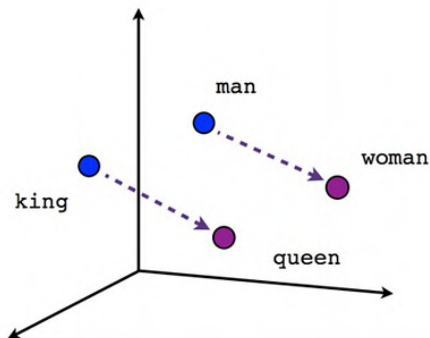
Gaussian Process Regression

“Prospecting” in concept-embedding space

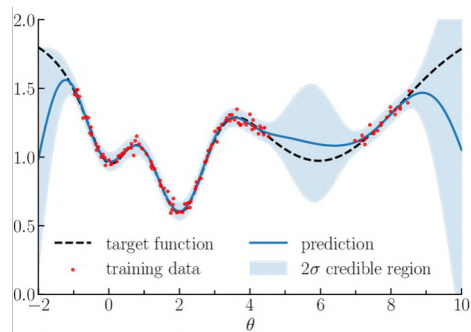


$\begin{bmatrix} 0 \\ 1.2 \\ 0 \\ 0 \\ \vdots \\ 0 \\ 1.9 \\ 0 \\ 0 \end{bmatrix}$

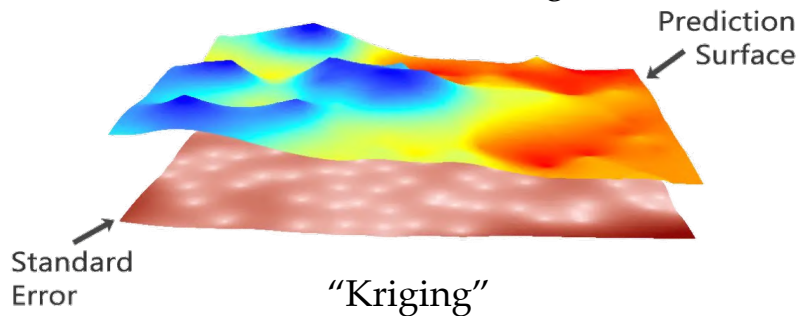
Observed concept rewards (sparse)



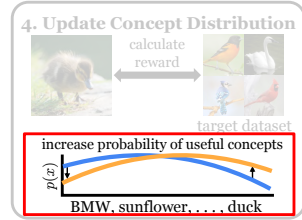
Sentence Transformer Embedding Space



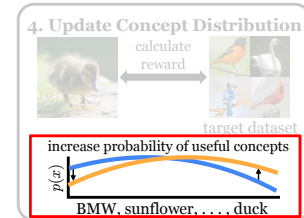
Gaussian Process Regression



Predicting Rewards / Forming Distribution



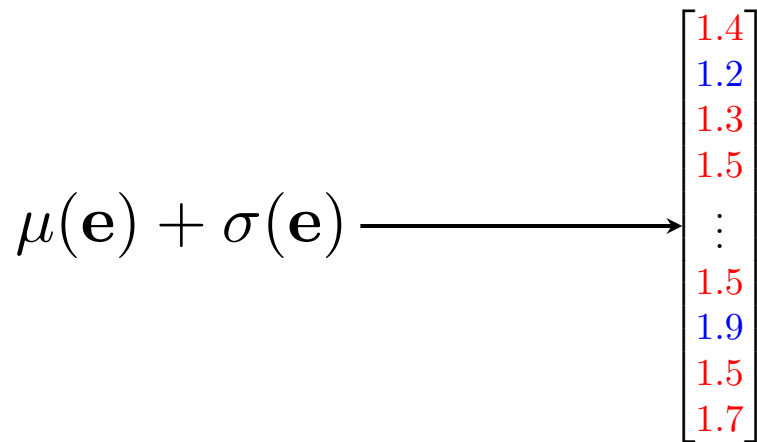
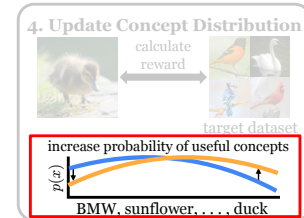
Predicting Rewards / Forming Distribution



$$\mu(\mathbf{e}) + \sigma(\mathbf{e})$$

Predicted concept
reward means &
stds. from GPR

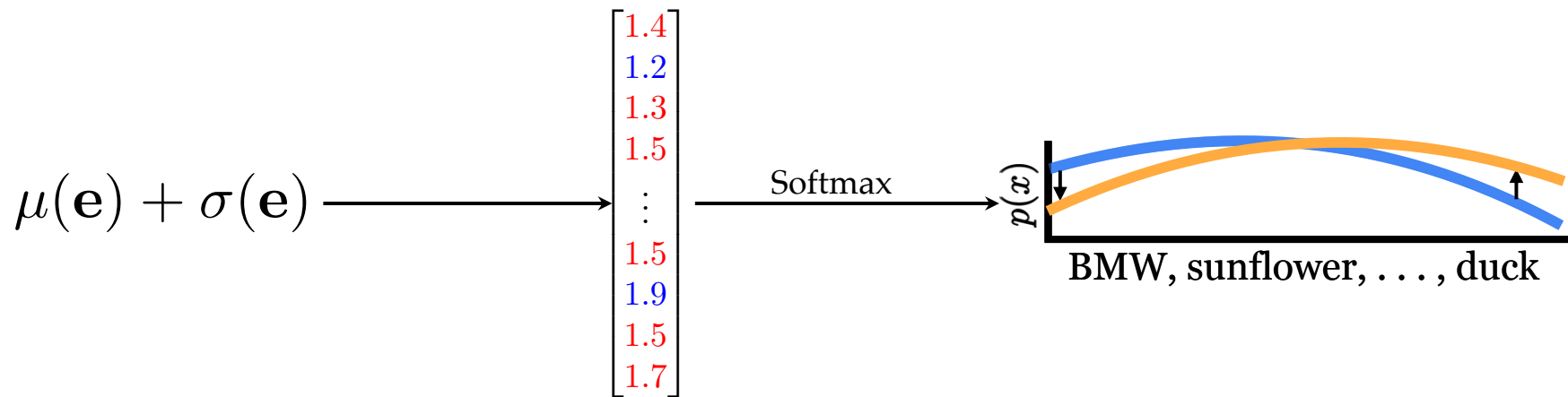
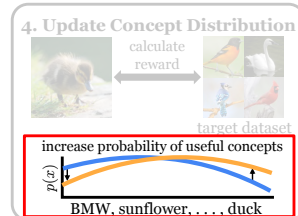
Predicting Rewards / Forming Distribution



Predicted concept
reward means &
stds. from GPR

Predicted concept
rewards (*dense*)

Predicting Rewards / Forming Distribution



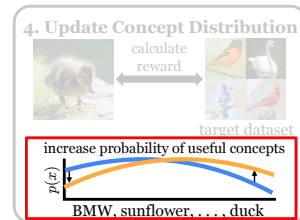
Predicted concept
reward means &
stds. from GPR

Predicted concept
rewards (*dense*)

Next iteration's
concept distribution

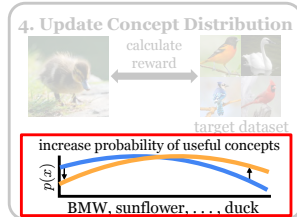
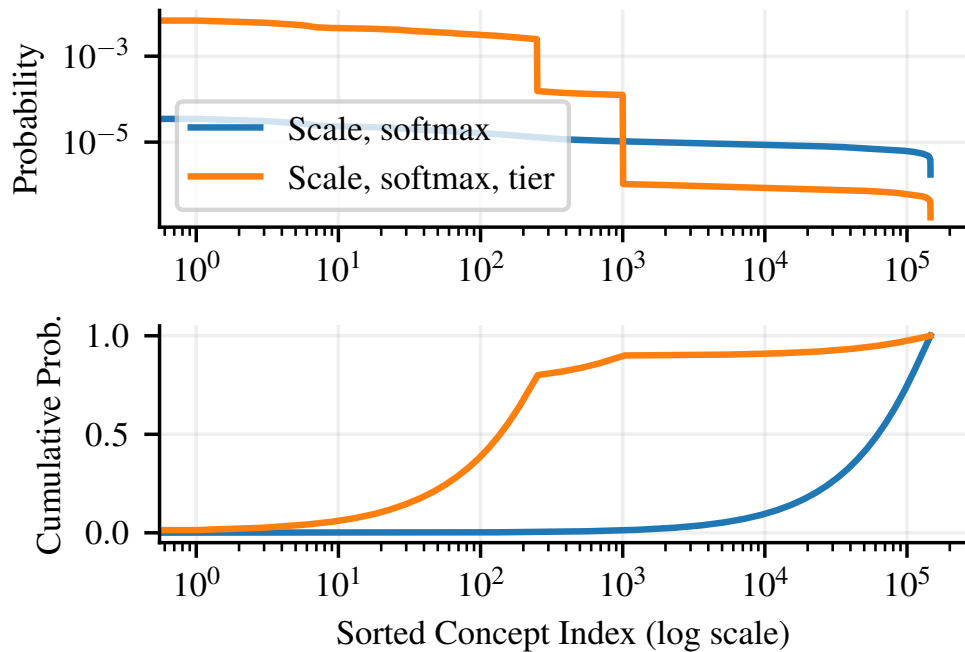
Tiering

150k concepts! Most relevant are *still* rarely sampled...



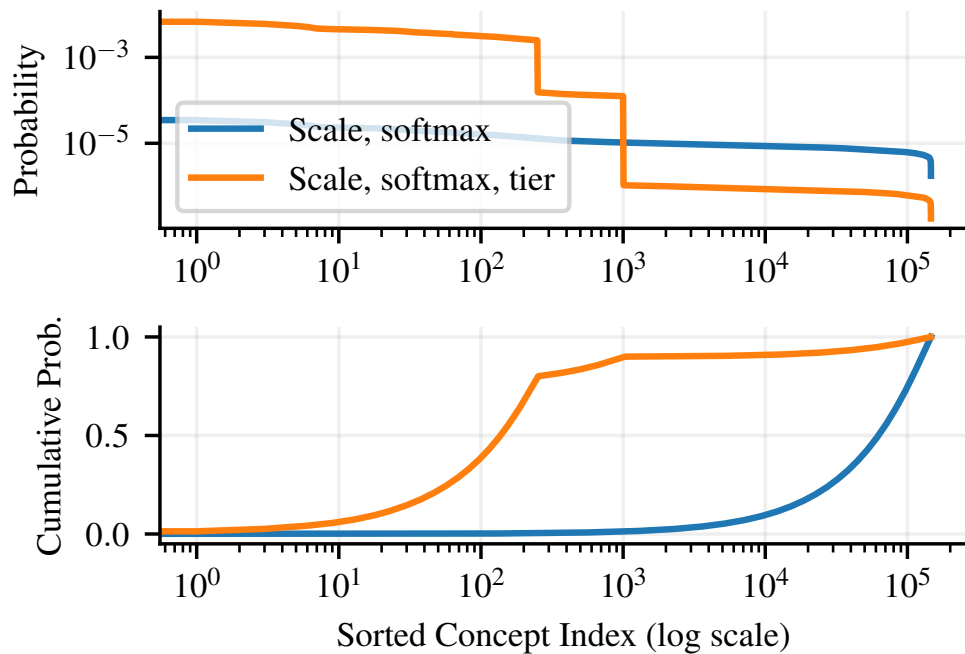
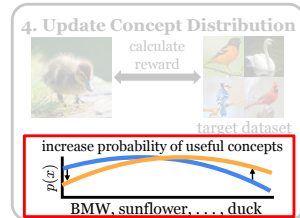
Tiering

150k concepts! Most relevant are *still* rarely sampled...



Tiering

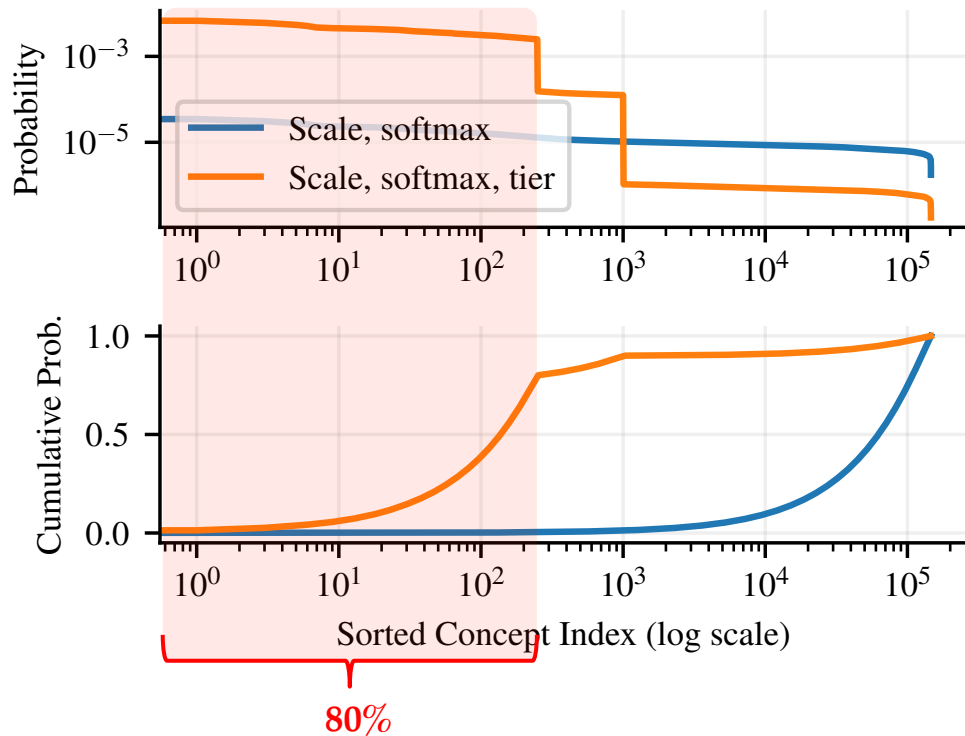
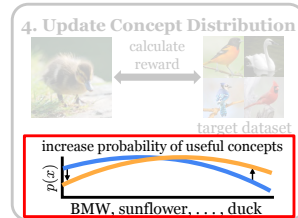
150k concepts! Most relevant are *still* rarely sampled...



Tiering

150k concepts! Most relevant are *still* rarely sampled...

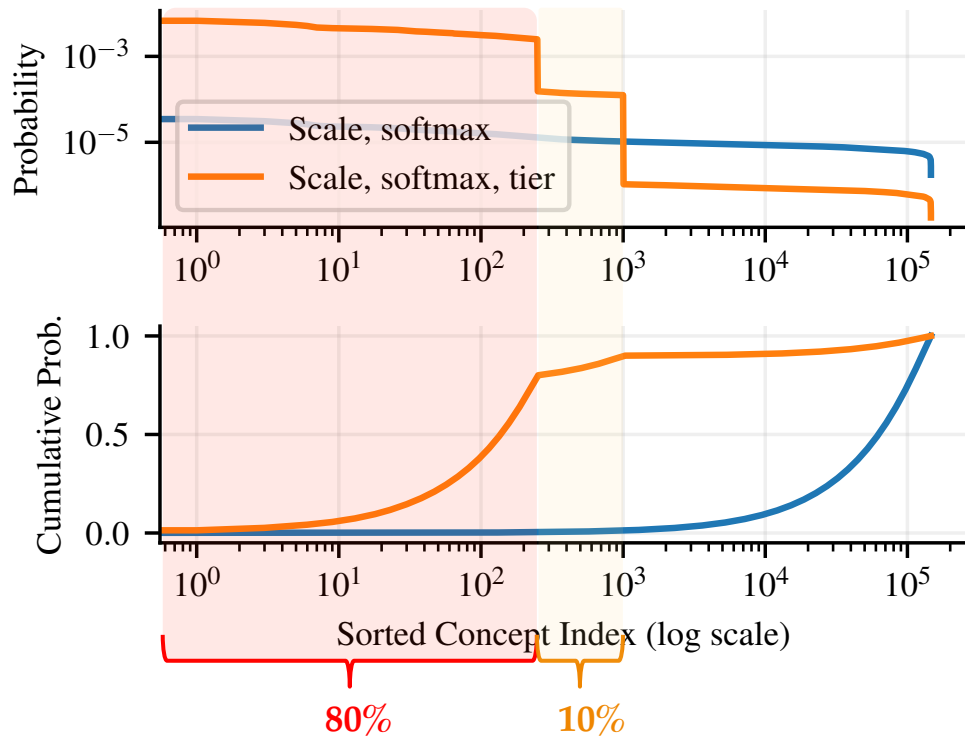
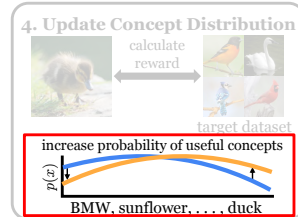
- Top 250 concepts sampled 80% of the time



Tiering

150k concepts! Most relevant are *still* rarely sampled...

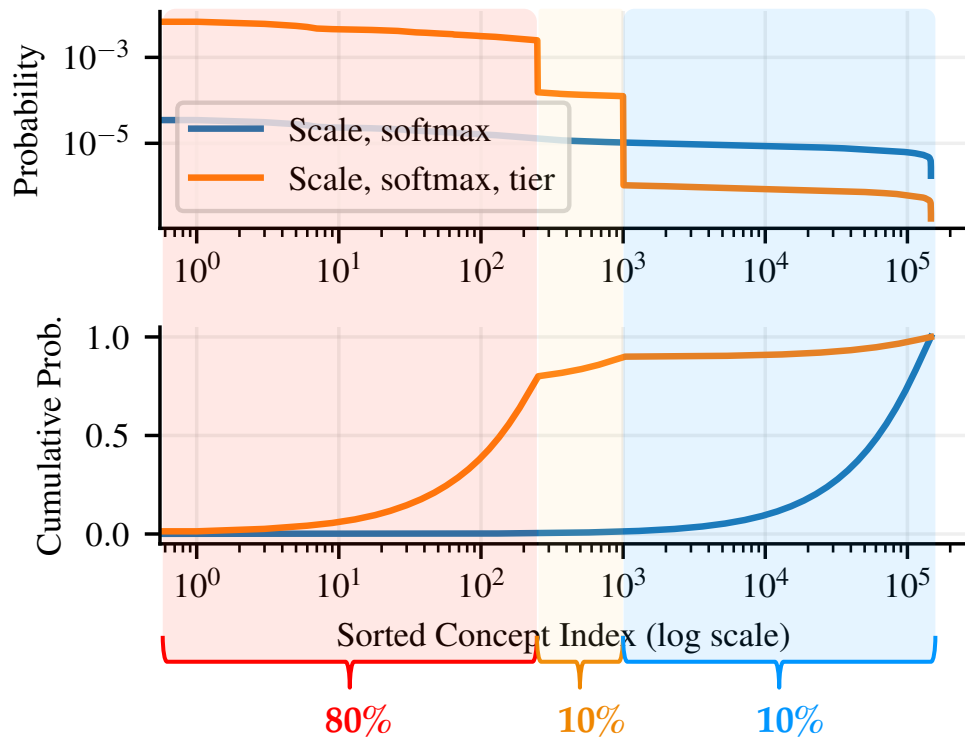
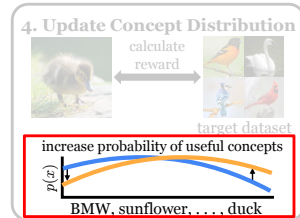
- Top 250 concepts sampled 80% of the time
- 251–1000 ranked concepts sampled 10% of the time



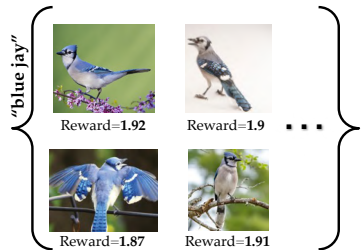
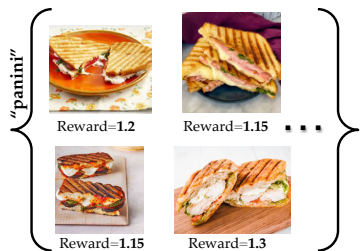
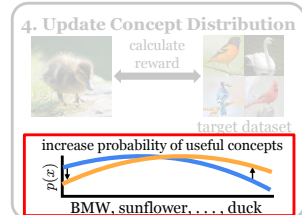
Tiering

150k concepts! Most relevant are *still* rarely sampled...

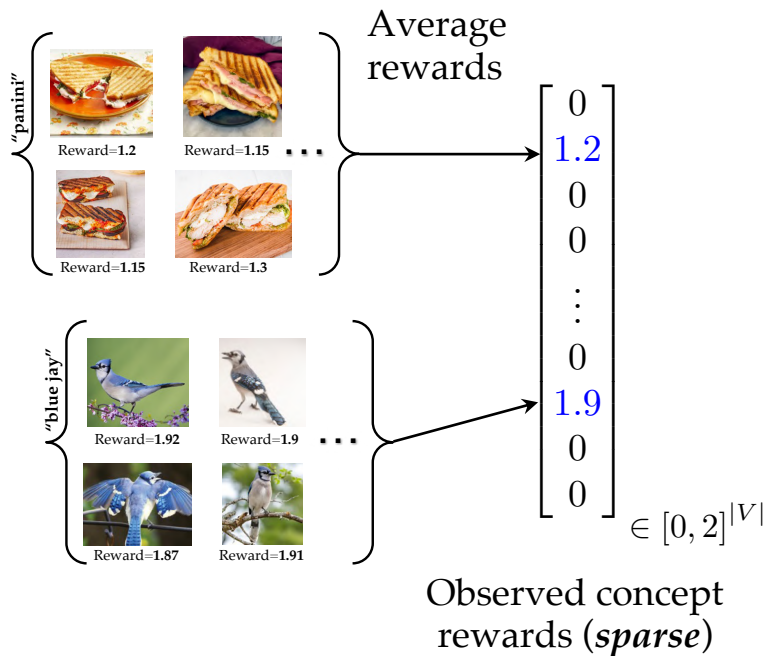
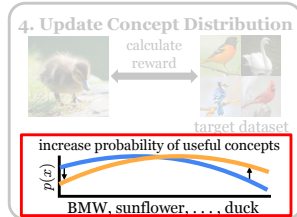
- Top 250 concepts sampled 80% of the time
- 251–1000 ranked concepts sampled 10% of the time
- Remaining concepts sampled 10% of the time



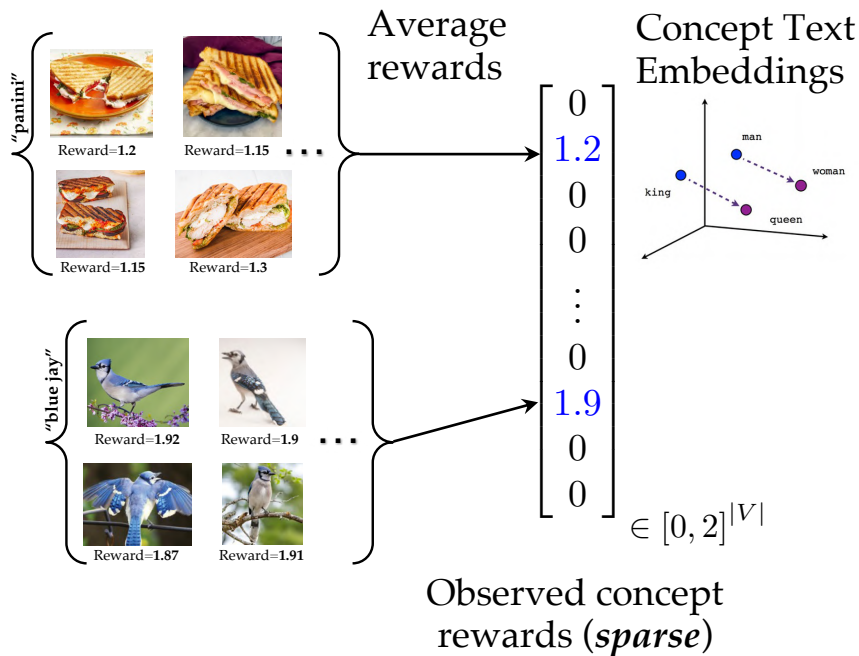
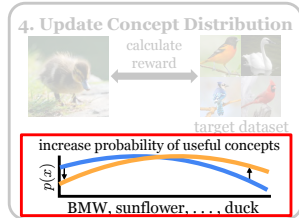
Recap: update dist. by predicting rewards



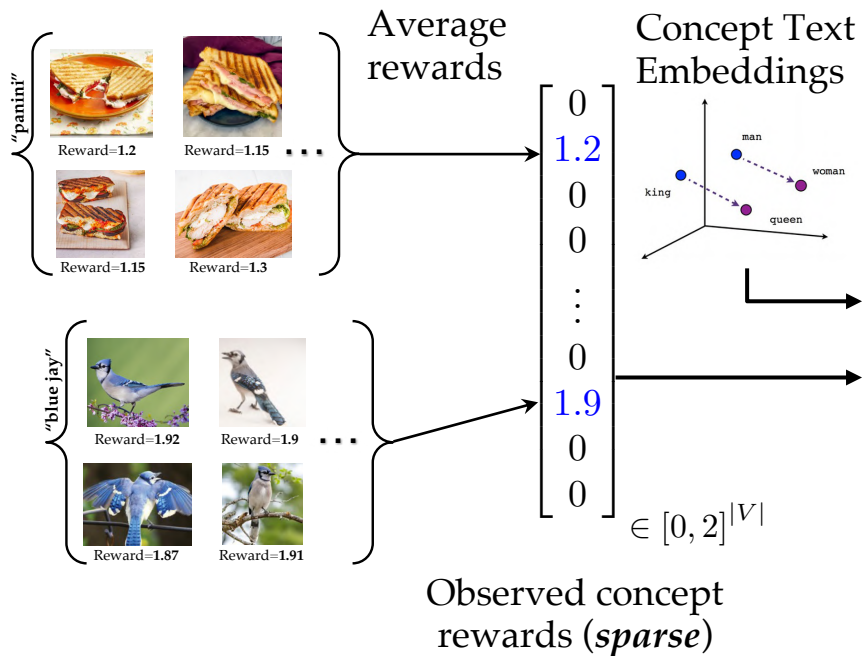
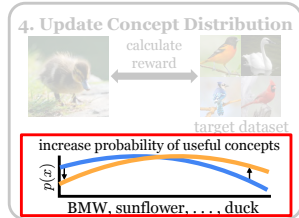
Recap: update dist. by predicting rewards



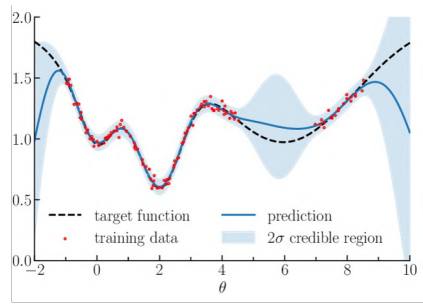
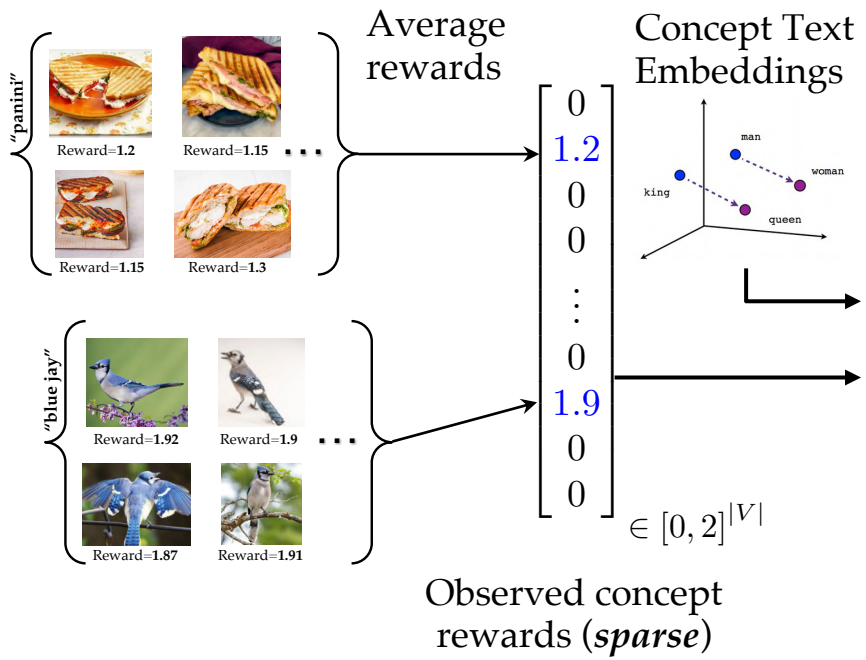
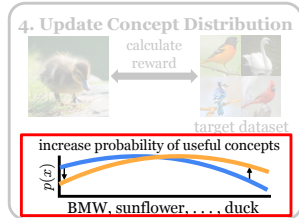
Recap: update dist. by predicting rewards



Recap: update dist. by predicting rewards

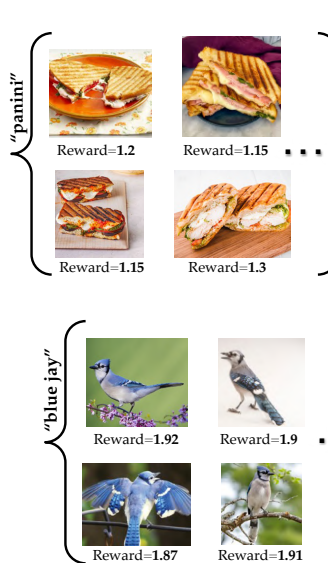
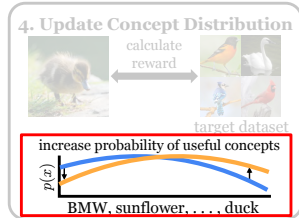


Recap: update dist. by predicting rewards



Gaussian Process Regression

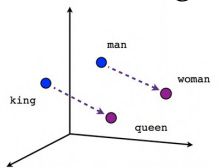
Recap: update dist. by predicting rewards



Average rewards

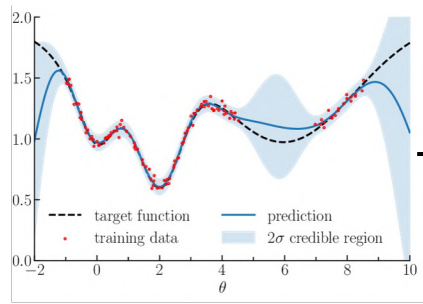
0
1.2
0
0
0
⋮
0
1.9
0
0

Concept Text Embeddings



Observed concept rewards (*sparse*)

$$\in [0, 2]^{|V|}$$

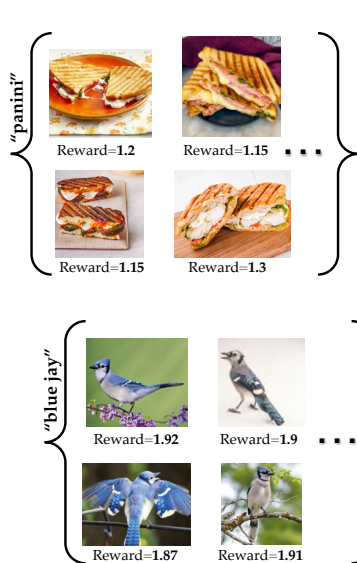
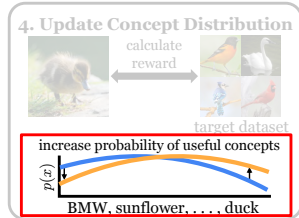


Gaussian Process Regression

1.4
1.2
1.3
1.5
⋮
1.5
1.9
1.5
1.7

Pred. concept rewards (*dense*)

Recap: update dist. by predicting rewards

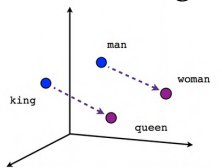


Average rewards

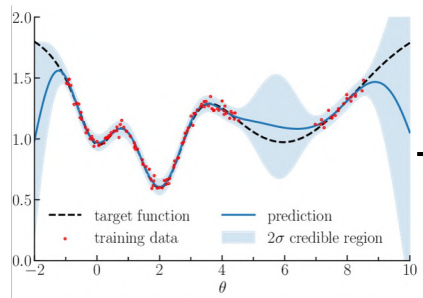
0
1.2
0
0
0
⋮
0
1.9
0
0
0

Observed concept rewards (*sparse*)

Concept Text Embeddings



$$\in [0, 2]^{|V|}$$

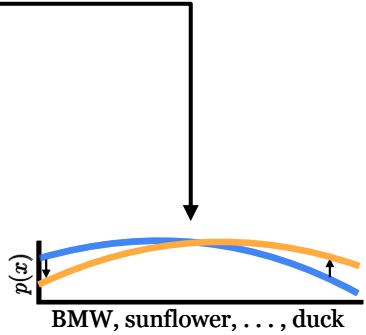


Gaussian Process Regression

1.4
1.2
1.3
1.5
⋮
1.5
1.9
1.5
1.7

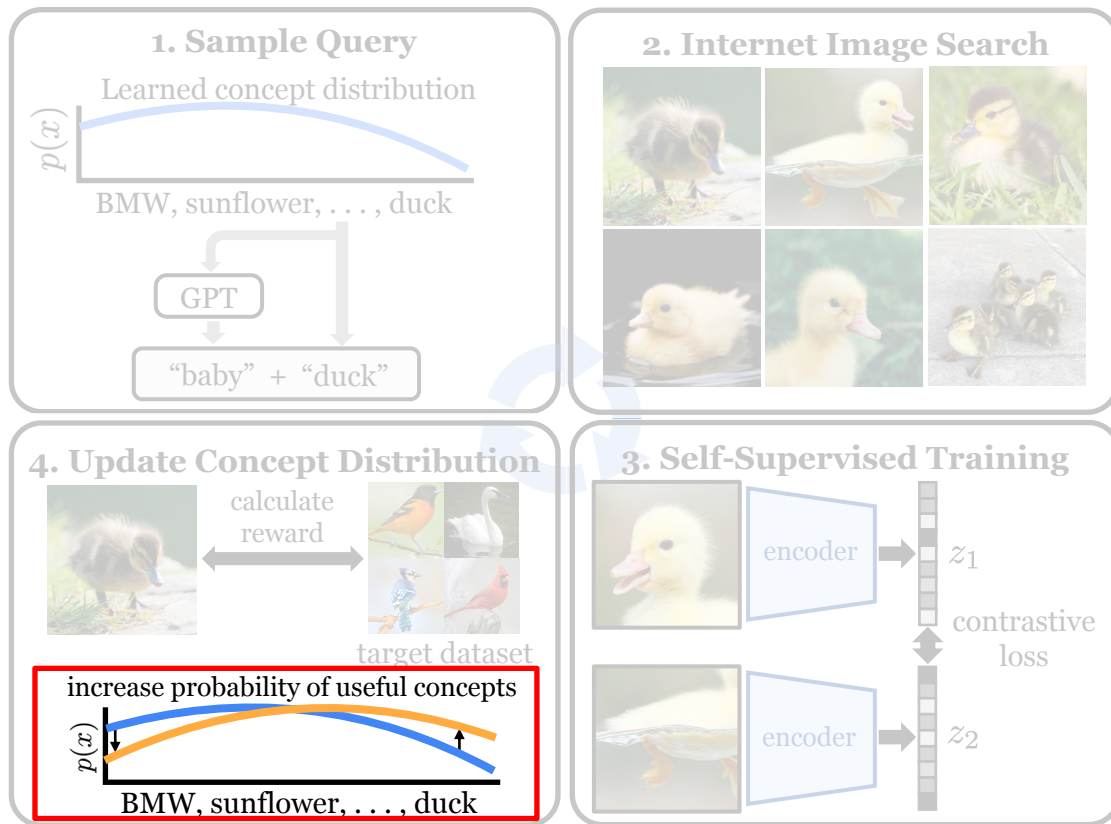
Pred. concept rewards (*dense*)

Softmax + Tier

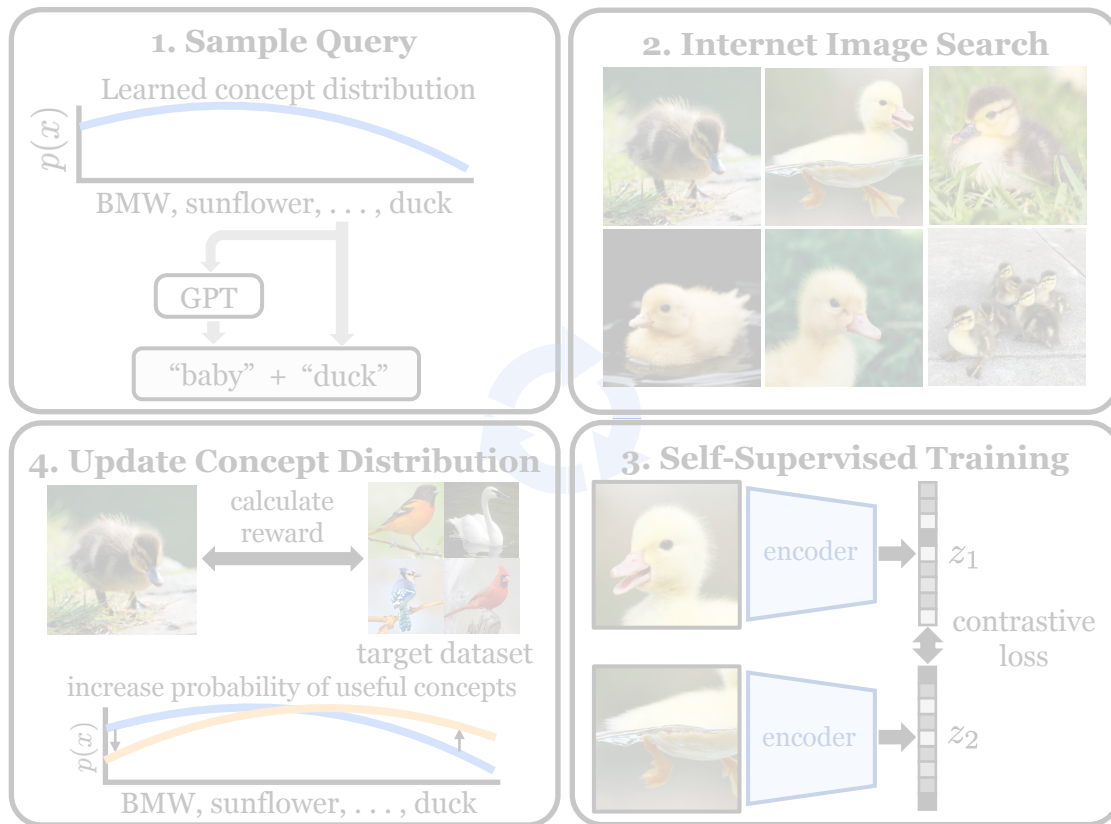


Next iter.'s concept dist.

Internet Explorer Method



Internet Explorer Method



What's changing over time?

What's changing over time?

What's changing over time?

Images that we search for and download

What's changing over time?

Images that we search for and download

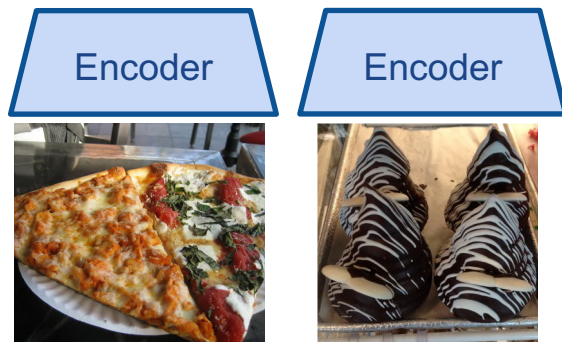
Representation space in which we compare images

Embedding space (and image reward) improves over time

Iteration 0:

Embedding space (and image reward) improves over time

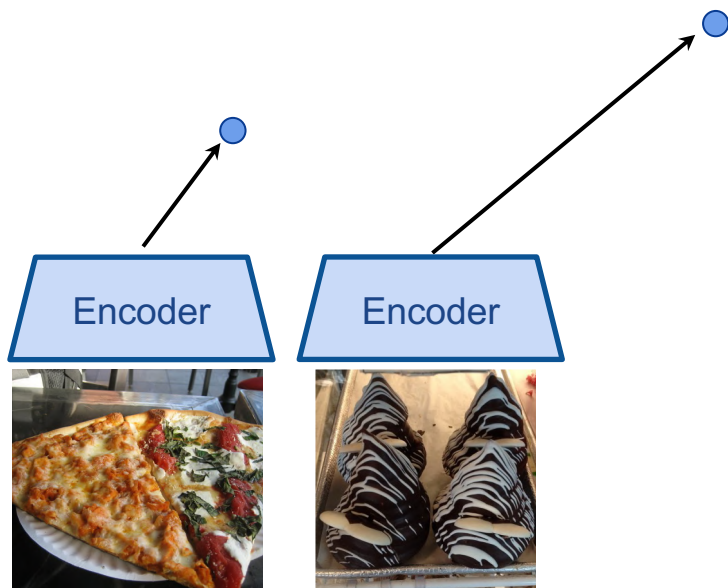
Iteration 0:



Target dataset images

Embedding space (and image reward) improves over time

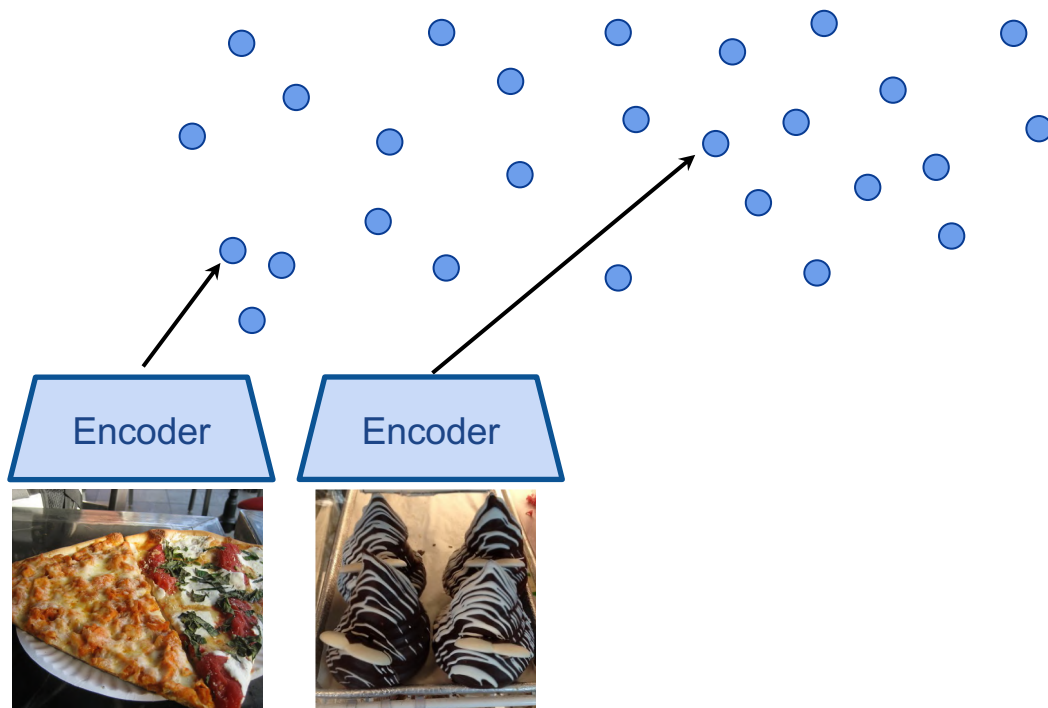
Iteration 0:



Target dataset images

Embedding space (and image reward) improves over time

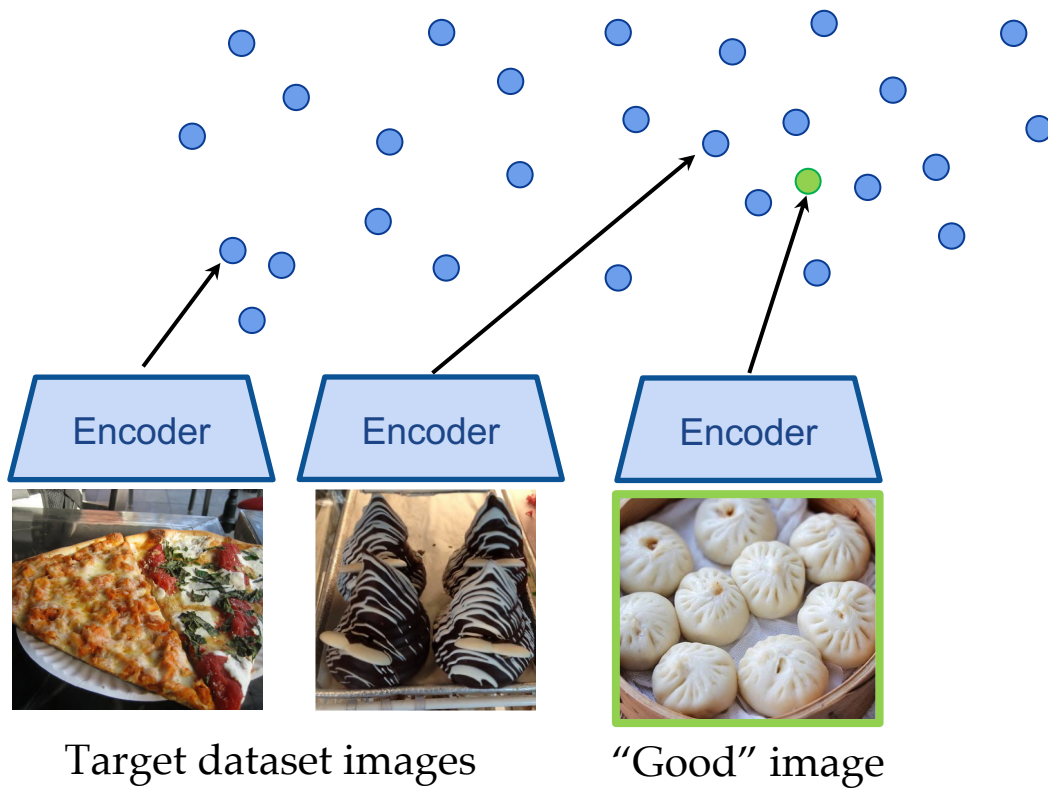
Iteration 0:



Target dataset images

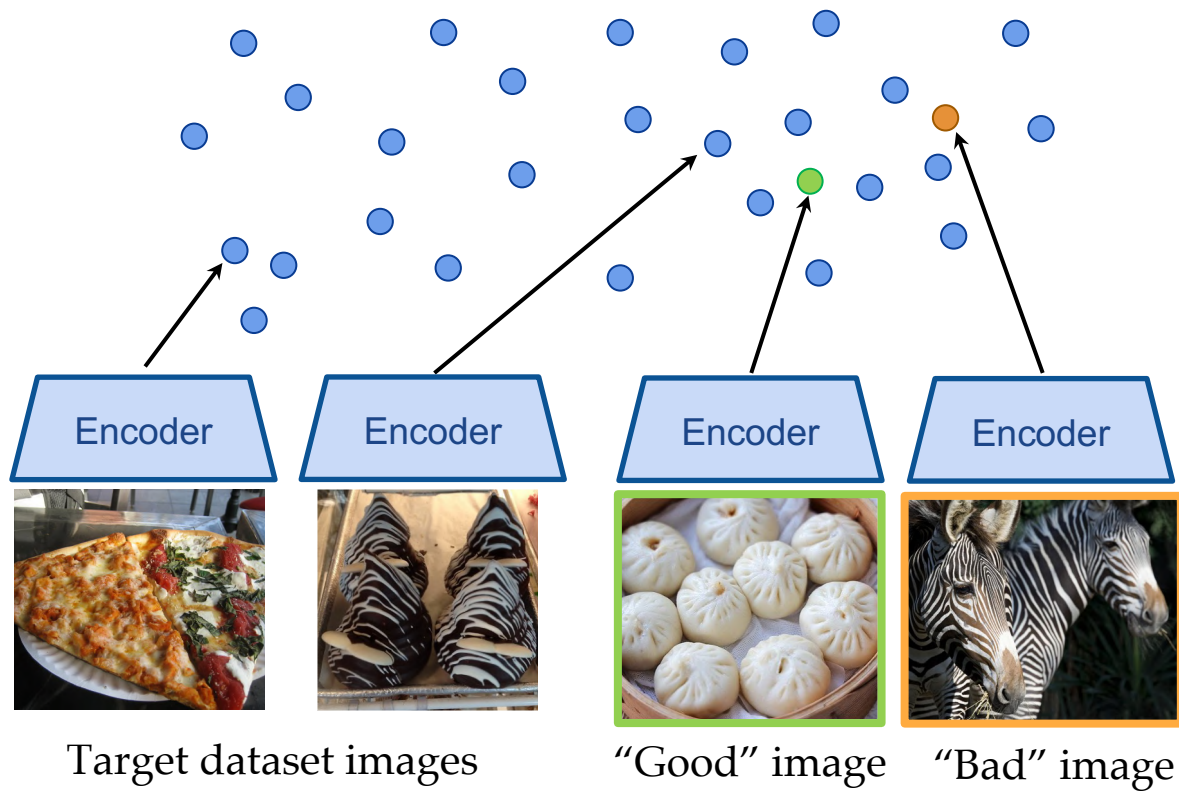
Embedding space (and image reward) improves over time

Iteration 0:



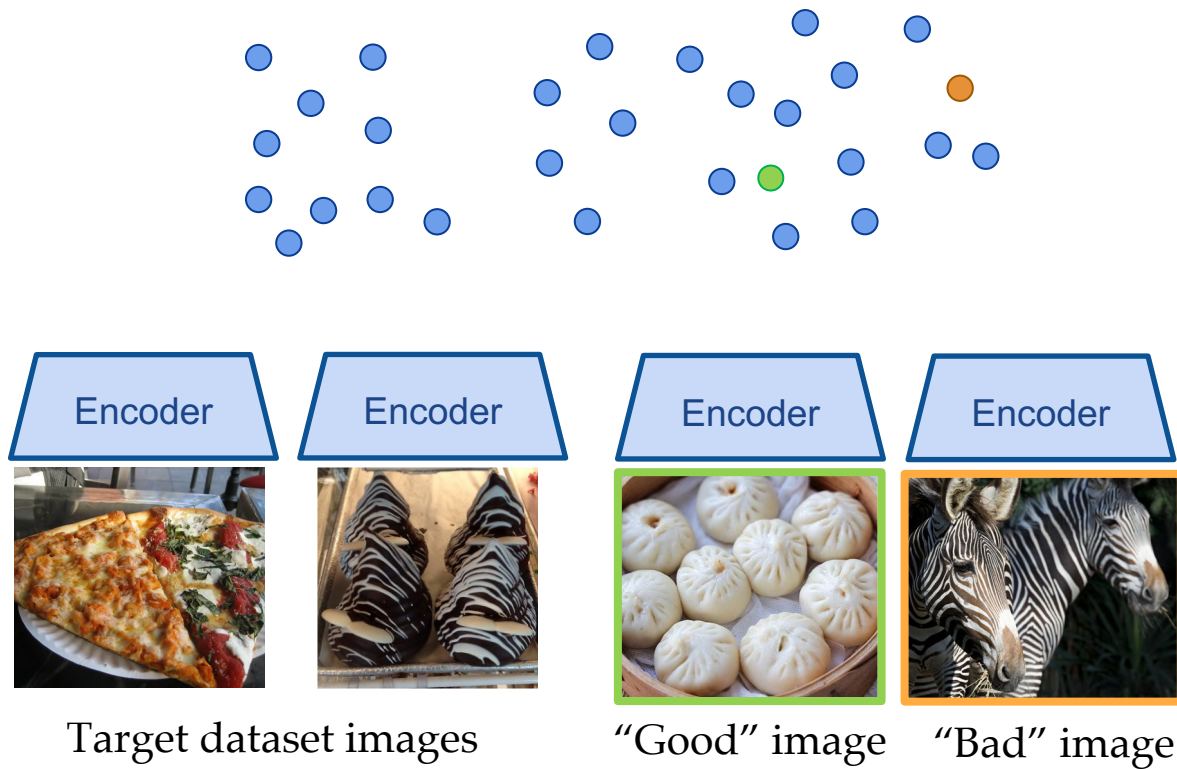
Embedding space (and image reward) improves over time

Iteration 0:



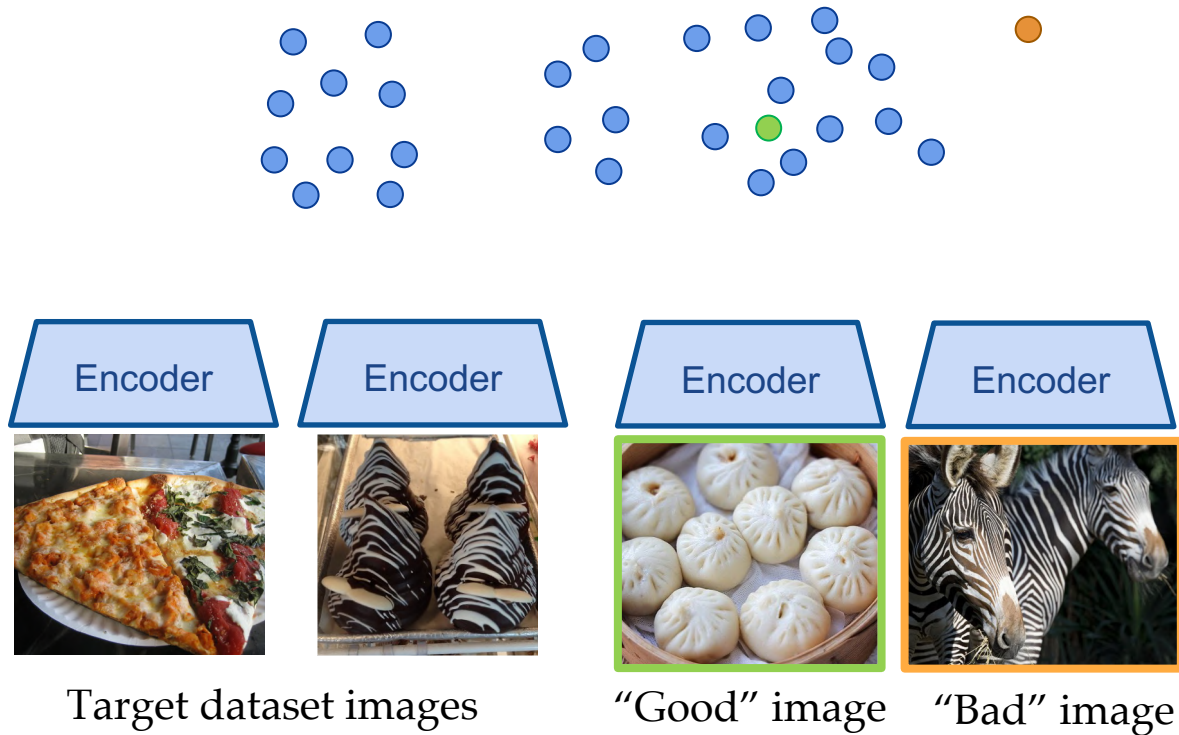
Embedding space (and image reward) improves over time

Iteration 5:



Embedding space (and image reward) improves over time

Iteration 10:



Results

Self-supervised exploration progressively finds relevant data

Self-supervised exploration progressively finds relevant data

Target dataset: Birdsnap



Self-supervised exploration progressively finds relevant data

Target dataset: Birdsnap



Iteration 0



Self-supervised exploration progressively finds relevant data

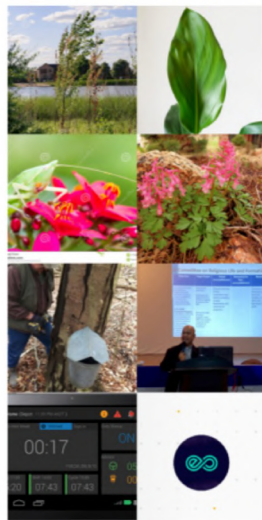
Target dataset: Birdsnap



Iteration 0



Iteration 1



Self-supervised exploration progressively finds relevant data

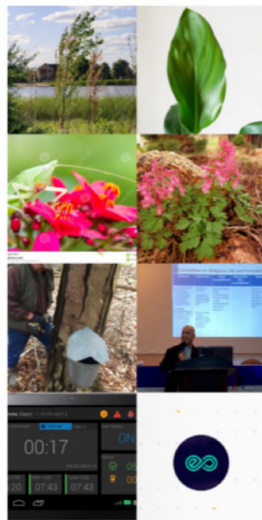
Target dataset: Birdsnap



Iteration 0



Iteration 1



Iteration 3



Self-supervised exploration progressively finds relevant data

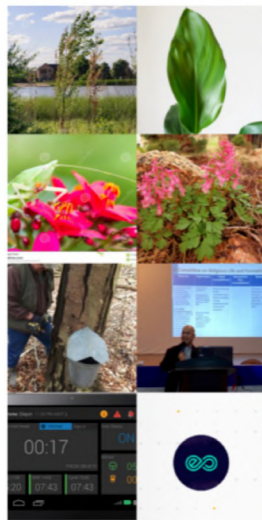
Target dataset: Birdsnap



Iteration 0



Iteration 1



Iteration 3



Self-supervised exploration progressively finds relevant data

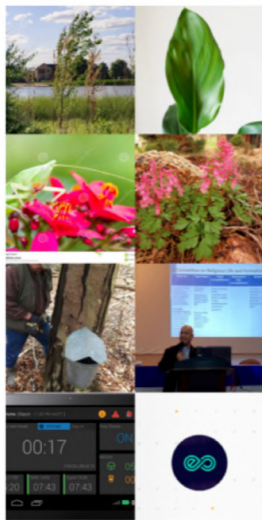
Target dataset: Birdsnap



Iteration 0



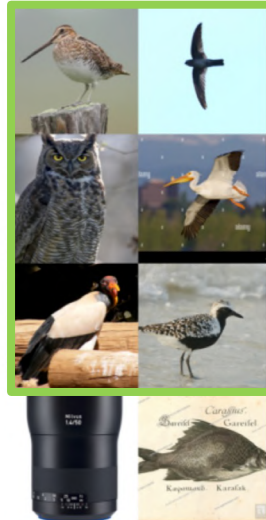
Iteration 1



Iteration 3



Iteration 6



Self-supervised exploration progressively finds relevant data

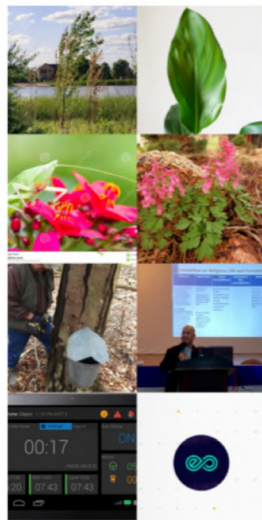
Target dataset: Birdsnap



Iteration 0



Iteration 1



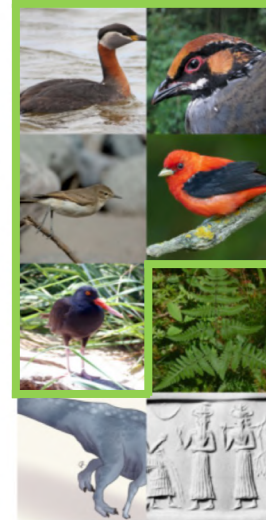
Iteration 3



Iteration 6



Iteration 10



Self-supervised exploration progressively finds relevant data

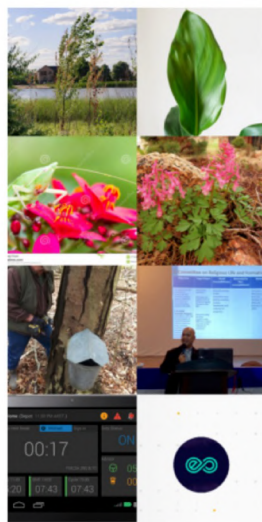
Target dataset: Birdsnap



Iteration 0



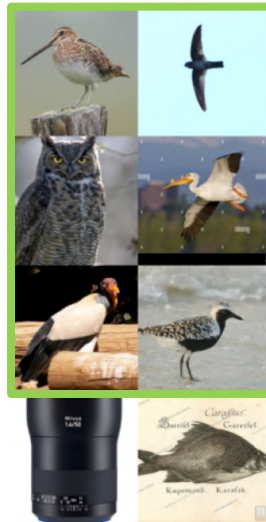
Iteration 1



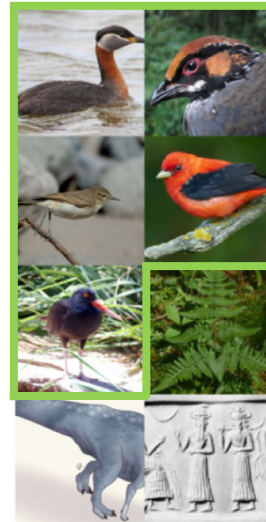
Iteration 3



Iteration 6



Iteration 10



Iteration 15



Internet Explorer outperforms fixed datasets

Model	Birdsnap	Flowers	Food	Pets	VOC2007	Images	GPU-hours
<i>Fixed dataset, self-supervised</i>							
MoCo-v3 (ImageNet + target)	39.9	94.6	78.3	85.3	58.0 [†]	1.2M	84

Table 1. Improved representation quality (linear probe accuracy) with Internet Explorer.

Internet Explorer outperforms fixed datasets

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Random exploration	39.6 (-0.3)	95.3 (+0.7)	77.0 (-1.3)	85.6 (+0.3)	70.2 (+12.2)	2.2M	124

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Search labels only	47.1 (+7.2)	96.3 (+1.7)	80.9 (+2.6)	85.7 (+0.4)	61.8 (+3.8)	2.2M	124

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+40 hrs on 1 GPU

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<i>Fixed dataset, language supervision</i>							
CLIP (oracle & 2x params)	57.1	96.0	86.4	88.4	86.7	400M	4000

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+40 hrs on 1 GPU

32x time, 180x data

Table 1. Improved representation quality (linear probe accuracy) with Internet Explorer.

Are we just finding the test images online?

Are we just finding the test images online?

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	Birdsnap	Flowers	Food	Pets	VOC2007	Images Downloaded
Target test set size	1849	6142	25246	3663	4952	—
<i>No exploration</i>						
Target training set overlap	1 (0.05%)	5 (0.01%)	34 (0.13%)	21 (0.57%)	0 (0.00%)	—

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<i>Internet Explorer</i>						
Ours++ (no label set)	28 (+1.46%)	11 (+0.01%)	35 (+0.00%)	26 (+0.14%)	1 (+0.02%)	$\approx 10^6$

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Ours++ (with label set)	57 (+3.03%)	27 (+0.36%)	35 (+0.00%)	43 (+0.60%)	1 (+0.02%)	$\approx 10^6$

But we are finding very relevant images...

Oxford-IIIT Pets



Test Img.

Ranked Nearest Neighbors in Downloaded Images

Food101



Test Img.

Ranked Nearest Neighbors in Downloaded Images

Oxford Flowers 102



Test Img.

Ranked Nearest Neighbors in Downloaded Images

VOC2007



Test Img.

Ranked Nearest Neighbors in Downloaded Images

Internet Explorer is robust to choice of search engine

Internet Explorer is robust to choice of search engine



Internet Explorer is robust to choice of search engine

Google



Bing

flickr

...

Internet Explorer is robust to choice of search engine

  Bing  ...

Q: do we rely on fancy tricks in modern search engines?

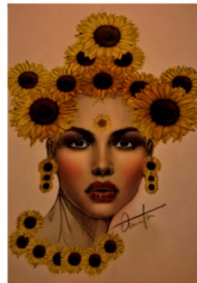
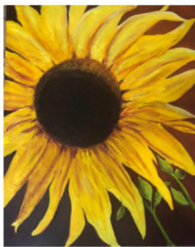
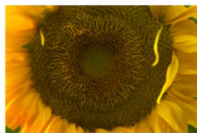
Internet Explorer is robust to choice of search engine



Q: do we rely on fancy tricks in modern search engines?

What if we could create our *own* search engine using just text?

Show me: sunflower



Similar trends

Model	Flowers	Food	Pets

Table 1. **Linear probe accuracy with other search engines.** Internet Curiosity improves its performance using any search engine, including Flickr and our custom text-only LAION search engine.

Similar trends

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	Google	Google	Google

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<i>Undirected search</i>						
Random exploration	95.3	95.2	77.0	80.0	85.6	84.4
<i>Internet Explorer</i>						
Ours++ (no label set)	98.4	98.1	81.2	80.3	87.3	88.4
Ours++ (with label set)	99.1	99.0	83.8	81.9	90.8	89.1

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Similar trends

Model	Flowers			Food			Pets		
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MoCo-v3 (IN)	83.2	83.2	83.2	70.5	70.5	70.5	79.6	79.6	79.6
MoCo-v3 (IN + target)	94.6	94.6	94.6	78.3	78.3	78.3	85.3	85.3	85.3
<i>Undirected search</i>									
Random exploration	95.3	95.2	94.8	77.0	80.0	80.2	85.6	84.4	85.1
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What's next on the open web?

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- Scale to larger / more diverse datasets like ImageNet

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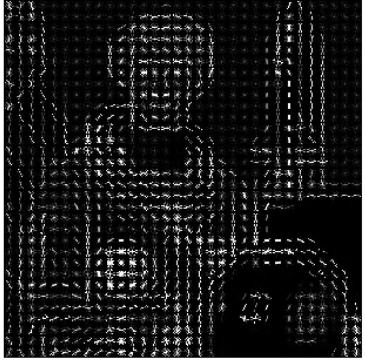
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- Apply to more challenging vision tasks, videos, and robotics

What's next on the open web?

- Scale to larger / more diverse datasets like ImageNet
- Apply to more challenging vision tasks, videos, and robotics
- Finetune a CLIP model online using captions + search terms!

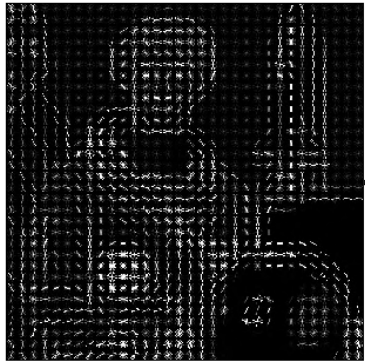
Deep Learning

Deep Learning



Handcrafted features

Deep Learning

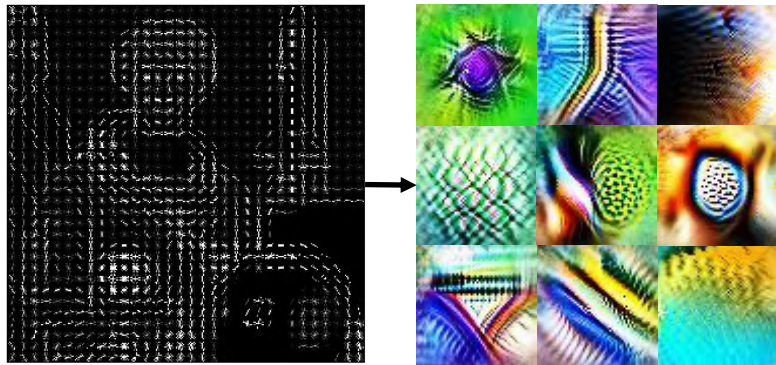


Handcrafted features



Model learns
features

Deep Learning

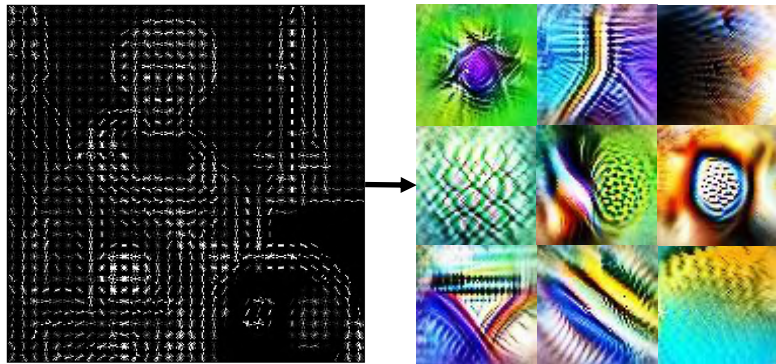


Handcrafted features

Model learns
features

Internet Explorer

Deep Learning



Handcrafted features

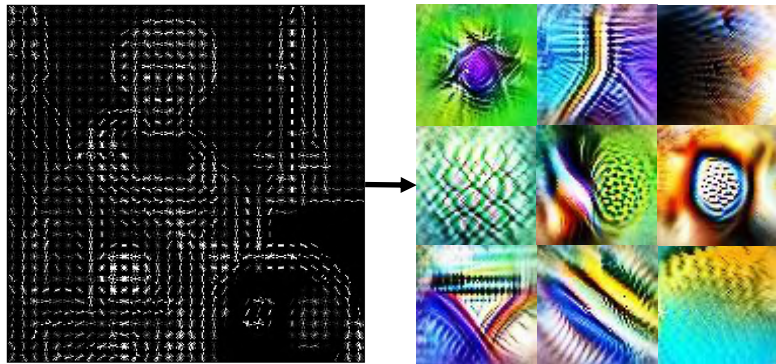
Model learns
features

Internet Explorer



Handcrafted dataset

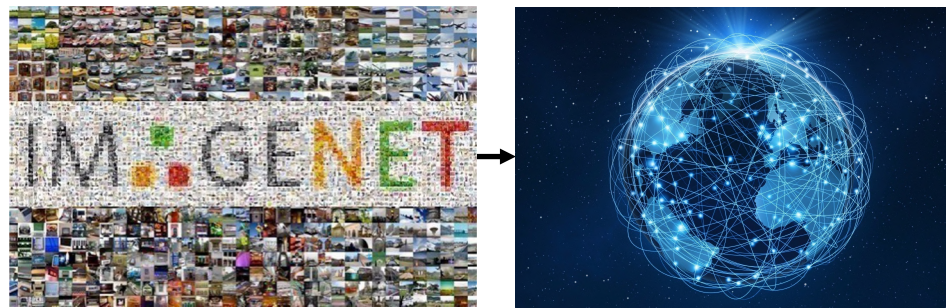
Deep Learning



Handcrafted features

Model learns
features

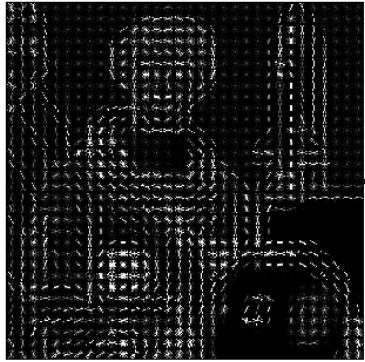
Internet Explorer



Handcrafted dataset

Model learns to craft
its own dataset

Deep Learning



Handcrafted features



Model learns
features

Internet Explorer



Handcrafted dataset



Model learns to craft
its own dataset

<http://internet-explorer-ssl.github.io>

Questions?

Your Diffusion Model is Secretly a Zero-Shot Classifier



Alexander C. Li Mihir Prabhudesai Shivam Duggal Ellis Brown Deepak Pathak

Carnegie Mellon University

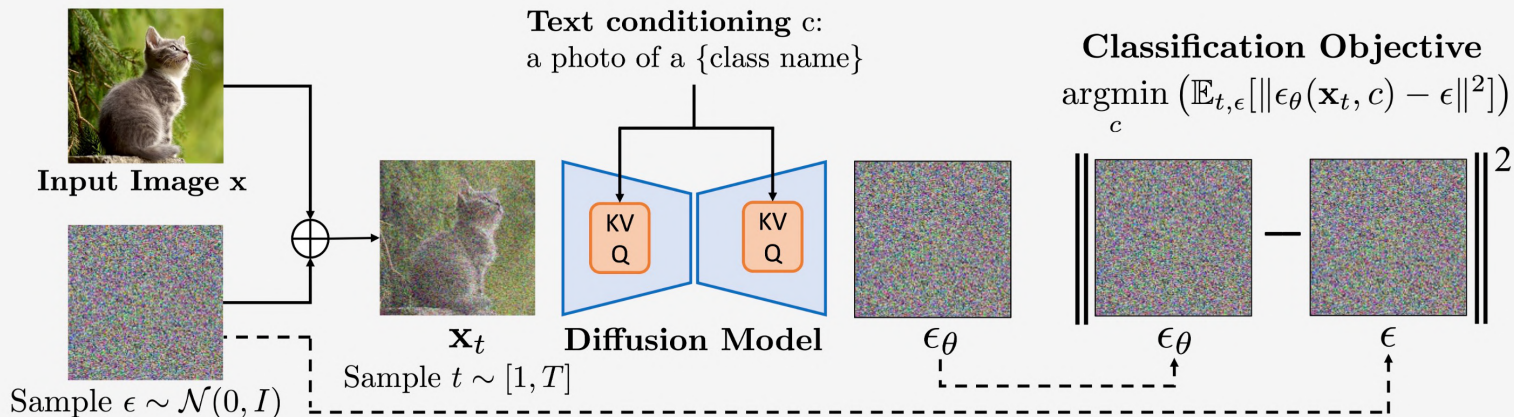
Your Diffusion Model is Secretly a Zero-Shot Classifier



Alexander C. Li Mihir Prabhudesai Shivam Duggal Ellis Brown Deepak Pathak

Carnegie Mellon University

"Diffusion Classifier"



Bayes' Rule + Generative Model \rightarrow Classification!

$$p_{\theta}(\mathbf{c}_i \mid \mathbf{x}) = \frac{p(\mathbf{c}_i) p_{\theta}(\mathbf{x} \mid \mathbf{c}_i)}{\sum_j p(\mathbf{c}_j) p_{\theta}(\mathbf{x} \mid \mathbf{c}_j)}$$

Bayes' Rule + Generative Model \rightarrow Classification!

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We use a **uniform label distribution** and a simple **approximate ELBO** to get:

$$p(\mathbf{c}_i) = \frac{1}{N}$$

$$\text{ELBO} \approx -\mathbb{E}_{t, \epsilon} [\|\epsilon - \epsilon_{\theta}(\mathbf{x}_t, \mathbf{c}_i)\|^2]$$

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$$p_{\theta}(\mathbf{c}_i \mid \mathbf{x}) \approx \frac{\exp\{-\mathbb{E}_{t,\epsilon}[\|\epsilon - \epsilon_{\theta}(\mathbf{x}_t, \mathbf{c}_i)\|^2]\}}{\sum_j \exp\{-\mathbb{E}_{t,\epsilon}[\|\epsilon - \epsilon_{\theta}(\mathbf{x}_t, \mathbf{c}_i)\|^2]\}}$$

Diffusion Classifier – OOD Generalization

	Zero-shot?	Food101	CIFAR10	FGVC	Oxford Pets	Flowers102	STL10	ImageNet	ObjectNet
Synthetic SD Data	✓	12.6	35.3	9.4	31.3	22.1	38.0	18.9	5.2
SD Features	✗	73.0	84.0	35.2	75.9	70.0	87.2	56.6	10.2
Diffusion Classifier (ours)	✓	77.9	87.1	24.3	86.2	59.4	95.3	58.9	38.3
CLIP ResNet-50	✓	81.1	75.6	19.3	85.4	65.9	94.3	58.2	40.0
OpenCLIP ViT-H/14	✓	92.7	97.3	42.3	94.6	79.9	98.3	76.8	69.2

Using **Stable Diffusion** as an image-text model

Diffusion Classifier – OOD Generalization

	Zero-shot?	Food101	CIFAR10	FGVC	Oxford Pets	Flowers102	STL10	ImageNet	ObjectNet
Synthetic SD Data	✓	12.6	35.3	9.4	31.3	22.1	38.0	18.9	5.2
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OpenCLIP ViT-H/14	✓	92.7	97.3	42.3	94.6	79.9	98.3	76.8	69.2

Using **Stable Diffusion** as an image-text model



Method	ID		OOD	
	IN	IN-v2	IN-A	ObjectNet
ResNet-18	74.1	57.3	15.0	26.6
ResNet-34	78.1	59.8	10.5	31.6
ResNet-50	79.7	61.6	9.8	35.6
ResNet-101	82.2	63.2	19.5	38.2
ViT-L/32	79.0	61.6	26.3	29.9
ViT-L/16	81.0	66.6	25.6	36.7
ViT-B/16	83.4	66.6	30.1	37.8
Diffusion Classifier	78.9	62.1	22.6	32.3

Using **Diffusion Transformers (DiT)** as a class-conditioned diffusion model

Table 3. **Diffusion Classifier performs well ID and OOD.**


Diffusion Classifier – Compositional Reasoning

✓ Diffusion Classifier ✓ OpenCLIP ✓ CLIP



"a bird eats a snake" "a snake eats a bird"

✓ Diffusion Classifier ✓ OpenCLIP ✗ CLIP




"there are more ladybugs than flowers" "there are more flowers than ladybugs"

✗ Diffusion Classifier ✗ OpenCLIP ✗ CLIP



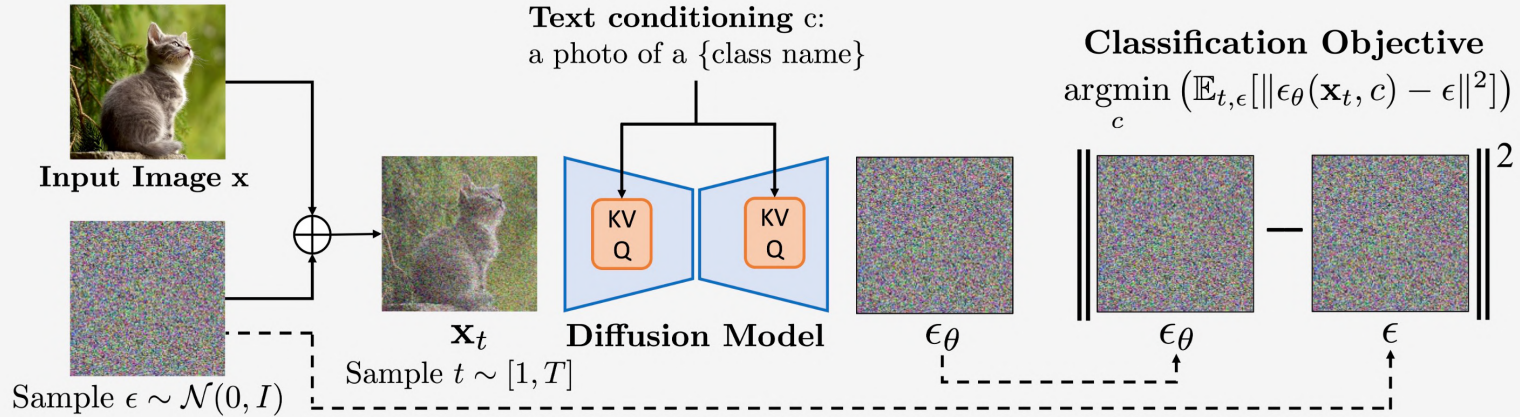
"the taller person hugs the shorter person" "the shorter person hugs the taller person"

✓ Diffusion Classifier ✗ OpenCLIP ✗ CLIP



"an old person kisses a young person" "a young person kisses an old person"

"Diffusion Classifier"



<https://diffusion-classifier.github.io/>

Acknowledgements



Deepak Pathak
(advisor)

Thank you, Thesis Committee!



Deepak Pathak
(advisor)

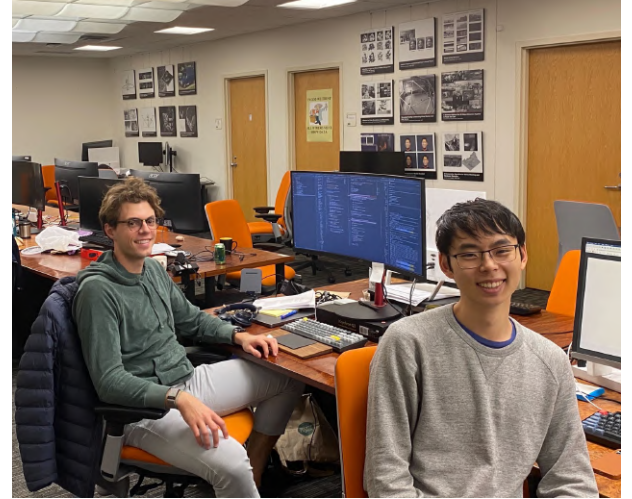


Deva Ramanan

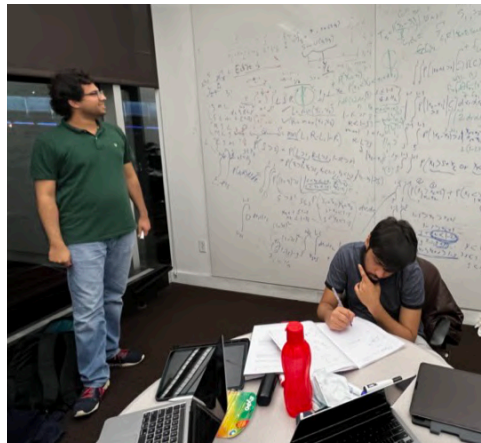


Alyosha Efros

Thank you, LEAP Lab!



Thank you, MSCS folks!



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